Double fins decelerator for blunt body in turbulent flows

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Abstract:- The work to be presented herein is a Computational Fluid Dynamics investigation of the complex fluid mechanisms that occur over blunt body with and without a decelerator, specifically with regard to the total aerodynamic drag. Drag is needed to decelerate the body. The aim of this research is to design deceleration devices for a blunt body. In this paper a qualitative analysis of the flow structure over a blunt body and blunt body with a double fins decelerator was shown. A drag over moving body consists of two components: pressure drag and friction drag. Drag is due to the effect of viscosity. Pressure drag is a result of the eddying motions that are generated in the fluid due to the movement of the body. Pressure drag is related to the cross-sectional area of the body and it is associated with the formation of a wake it is also important for separated flows. Frictional drag is a result of the flow and it is associated with the development of boundary layers it is also important for attached flows.

For a blunt body, pressure drag is the dominant source of drag, but for streamlined body friction drag is the dominant source of air resistance. In some applications of aerodynamics, a deceleration of a moving body is required therefore the prediction and controlling of the drag is essential. The deceleration devices such as air bag or fins can be added to the body to increase the aerodynamics drag.

For a supersonic speed, a flow around blunt body is complicated due to the detached shock wave, flow separation, boundary layer and their interactions. When a decelerator is integrated with the blunt body the flow is subject to sever change of aerodynamic forces and velocity.

The results will show, that the adding a deceleration device will change the flow structure behind the body especially with regard to the pressure drag and wake. Results of contour plots of static pressure, static temperature, and Mach number for zero angles of attack will demonstrate that the aerodynamic forces and the velocity are changed when the deceleration device is integrated with the blunt body.

Key- Words: Compressible flow, bow shock, detached shock, numerical analysis, CFD, high speed flow, turbulent flow.

Introduction

The work to be presented herein is a Computational Fluid Dynamics investigation of the complex fluid mechanisms that occur over blunt body with and without a decelerator, specifically with regard to the total aerodynamic drag. Drag is needed to decelerate the body. The aim of this research is to design deceleration devices for a blunt body. In this paper an analysis of the flow structure over a blunt body and blunt body with a decelerator was shown.

A drag over moving body consists of two components: pressure drag and friction drag. Drag is due to the effect of viscosity. Pressure drag is a result of the eddying motions that are generated in the fluid due to the movement of the body. Pressure drag is related to the cross-sectional area of the body and it is associated with the formation of a wake it is also important for separated flows. Frictional drag is a result of the friction between the fluid and the surfaces over which it is flowing. Frictional drag is related to the surface area exposed to the flow and it is associated with the development of boundary layers it is also important for attached flows [1-2].

For a blunt body, pressure drag is the dominant source of drag, but for streamlined body friction drag is the dominant source of air resistance. In some applications of aerodynamics, a deceleration of a moving body is required therefore the prediction and controlling of the drag is essential [3]. The deceleration devices such as air bag or fins can be added to the body to increase the aerodynamics drag.

For a supersonic speed, a flow around blunt body is complicated due to the detached shock wave, flow separation, boundary layer and their interactions. When a decelerator is integrated with the blunt body the flow is subject to sever change of aerodynamic forces and velocity [4-5].

A number of important conclusions follow from the current research. First, study of the actual flow configuration over a blunt body with a decelerator offers some insight into the complex flow phenomena. Second, adding the decelerator will increase the separation that will result in an increase of total drag.

Computational Fluid Dynamics Analysis

The governing equations are a set of coupled nonlinear, partial differential equations. In order to formulate or approximate a valid solution for these equations they must be solved using

computational fluid dynamics techniques. To solve the equations numerically they must be discretized. That is, the continuous control volume equations must be applied to each discrete control volume that is formed by the computational grid. The integral equations are replaced with a set of linear algebraic equations solved at a discrete set of points.

Fluent is used in this current research to model the flow characteristics over blunt body. Fluent uses unstructured mesh that can be generated for complex geometry. Supported mesh types include 3D tetrahedral/ hexahedral/ pyramid/ wedge, and hybrid meshes. Fluent allows to refine grid based on the flow solution and has the capability of true dynamic memory allocation, efficient data structures, and flexible solver control. The code solves the three-dimensional Navier-Stokes equations by utilizing finite volume method over unstructured grids. The CFD code is an integrated software system capable of solving diverse and complex multidimensional fluid flow problems. The fluid flow solver provides solutions compressible, steadystate or transient, laminar or turbulent single-phase fluid flow in complex geometries.

Creating the grid is the first step in calculating a flow. Three-dimensional Navier Stokes equations are solved using coupled implicit scheme with Spalart-Allmaras (1 Equation with vorticity-Based Production) turbulence model. The grid is refined near the surfaces and in front of the body in order to model the large gradient.

It should be possible to model the detached shock waves, flow separation, the interaction of the shock waves, and expansion fans around the blunt body with the decelerator using the CFD analysis [6-10]



Fig.1 Schematic view of a blunt body without decelerator showing a 2-D unstructured mesh



Figure2: Schematic view of a blunt body with double fins decelerator showing a 2-D unstructured mesh

A computational model that illustrates the physics of flow over double step and opposed wedges was developed. Through this computational analysis, a better interpretation of this physical phenomenon can be achieved. The results from the numerical analysis will be used to develop a design methodology so as to predict optimal performance.

Results and discussion

Figure 1 shows a two dimensional unstructured mesh. Figure 1 also shows a schematic view of the blunt body without decelerator. Figure 2 shows a two dimensional unstructured mesh of blunt body with double fins decelerator. The analysis was carried out based on the flow over the blunt body without a decelerator and with double fins decelerator for a Mach number of 1.5.

Figure 3 shows a contour plot of Mach number for flow over a blunt body without a decelerator at zero angle of attack. One can see the detached shock waves in figure 3. One can also notice from this figure that the shape and the strength of the detached shock waves and flow separation region. Figure 4 shows contour plot of static pressure for flow over blunt body without a decelerator. One can see the detached shock wave generation.



Figure 3: Contour plot of Mach number, flow over blunt body without decelerator



body without a decelerator



body with double fins decelerator



Figure 5 shows a contour plot of Mach number for flow over a blunt body with a double fins decelerator at zero angle of attack. The Mach number is 1.5. One can see the detached shock waves in figure 5. One can also notice from this figure that the shape and the strength of the detached shock waves and flow separation region. It is observed, from figure 5 that adding a decelerator can lead to significant increase in flow separation behind the body.

Contour plot of static pressure for flow over a blunt body with a double fins decelerator at zero angle of attack is shown in figure 6. The Mach number is 1.5. One can see the detached shock waves in figure 6. One can also notice from this figure that the shape and the strength of the detached shock waves and flow separation region. It is observed, from figure 5 that adding a decelerator can lead to significant increase in flow separation behind the body.

Figure 7 shows a plot of drag coefficient for the flow over a blunt body without a decelerator and the numerical value is 0.090. Figure 8 shows a plot of drag coefficient for the flow over a blunt body with a double fins decelerator and the numerical value is 0.12. One can say from studying figures 7 and 8 that adding double fins decelerator of this shape (showing in figure 2) will add almost 25 % drag.

Conclusion

A computational model that illustrates the physics of flow through shock waves, expansion fans and slip surfaces was developed. The flow is compressible viscous high speed. In this situation, one should expect oblique shock waves, expansion fans, shock wave interactions, and slip surface generation.

The results will show that adding a double fins deceleration device will change the flow structure behind the body especially with regard to the pressure drag and wake. Results of contour plots of static pressure, static temperature, and Mach number for zero angles of attack will demonstrate that the aerodynamic force and the velocity are changed when the deceleration device is integrated with the blunt body. Finally, one can conclude from studying figures 7 and 8 that adding double fins decelerator of this shape (showing in figure 2) will add almost 25 % drag.

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