Piecewise polynomial approximations for weakly singular integral equations with discontinuous coefficients

KRISTIINA HAKK¹, ARVET PEDAS² ¹Estonian Information Technology College Rävala 14, 10143 Tallinn ² University of Tartu Liivi 2, 50409 Tartu ESTONIA kristiina.hakk@itcollege.ee, arvet.pedas@ut.ee

Abstract: – We study the attainable order of a piecewise polynomial collocation method for the numerical solution of linear integral equations with weakly singular or other nonsmooth kernels. In particular, the kernel may have the form $K(t,s) = g(t,s)|t-s|^{-\nu}$, $0 < \nu < 1$, where g is proposed to be smooth only on $[0,b] \times ([0,b] \setminus \{d\}), 0 < d < b$. We show that the proposed method is of maximal possible order if the grid is chosen appropriately.

Key words: - Fredholm integral equation, weakly singular kernel, collocation method.

1 Introduction

Let $\mathbb{R} = (-\infty, \infty)$, $\mathbb{N} = \{1, 2, \ldots\}$, $\mathbb{N}_0 = \{0\} \cup \mathbb{N}$. For $\Omega \subset \mathbb{R}^n$, by $C^m(\Omega)$ we denote the set of m times continuously differentiable functions $x : \Omega \to \mathbb{R}$, $C^0(\Omega) = C(\Omega)$. The set C[a, b] of continuous functions $x : [a, b] \to \mathbb{R}$ is a Banach space with respect to the norm $||x||_{C[a,b]} = \max_{a \le t \le b} |x(t)|$.

Let us consider an integral equation of the form

$$u(t) - \int_{0}^{b} K(t,s)u(s)ds = f(t), \ 0 \le t \le b, \quad (1)$$

with $f \in C[0, b]$ and $K(t, s) = g(t, s)|t - s|^{-\nu}$, $0 < \nu < 1$, where g is a sufficiently smooth function on $[0, b] \times [0, b]$. Solutions of integral equations of this type will in general contain singularities in their derivatives at the endpoints of the interval [0, b], even for smooth forcing functions f(see, for example, [1,5,6]). Therefore difficulties in constructing of high order numerical methods for solving (1) arise. To overcome these difficulties, one can thicken near 0 and b, the grid which is used to built approximate solution [1,5,6].

In the present paper we study the case if g is proposed to be smooth only on $[0, b] \times ([0, b] \setminus \{d\})$, with $d \in (0, b)$. In this case the derivatives of the solution u(s) of equation (1) may have singularities at s = d, also [4,5]. Therefore, to get numerical algorithms of higher order for solving (1), we shall thicken the grid near s = d, too. In fact, we shall construct a piecewise polynomial collocation method for the numerical solution of a wide class of weakly singular integral equations and show that it is of maximal possible order if the grid is chosen appropriately.

2 Smoothness of the solution

We consider a kernel K in the form

$$K(t,s) = g(t,s)\kappa(t,s) \tag{2}$$

with g and κ satisfying the following assumptions (A1) and (A2), respectively.

- (A1) The function g = g(t, s) is m times $(m \ge 1)$ continuously differentiable with respect to tand s for $t \in [0, b], s \in [0, b] \setminus \{d\}, 0 < d < b$, and its derivatives are bounded in the regions $[0, b] \times [0, d)$ and $[0, b] \times (d, b]$. Let p $(0 \le p \le m)$ be an integer defined as follows: p = 0 if g may have a discontinuity across the line $s = d; p \ge 1$ if $g \in C^{p-1}([0, b] \times [0, b])$.
- (A2) The function $\kappa = \kappa(t, s)$ is m times (m is fixed in the assumption (A1)) continuously differentiable with respect to t and s for $t, s \in [0, b], t \neq s$, and there exists a real

number $\nu, -\infty < \nu < 1$, such that the estimate

$$\begin{split} & \left| \left(\frac{\partial}{\partial t} \right)^{i} \left(\frac{\partial}{\partial t} + \frac{\partial}{\partial s} \right)^{j} \kappa(t, s) \right| \leq \\ & c \begin{cases} 1, & \text{if } \nu + i < 0, \\ 1 + |\ln|t - s||, & \text{if } \nu + i = 0, \\ |t - s|^{-\nu - i}, & \text{if } \nu + i > 0, \end{cases} \tag{3}$$

holds with a positive constant c for all $t, s \in [0, b], t \neq s$ and for all $i, j \in \mathbb{N}_0, i + j \leq m$.

For i = j = 0, condition (3) yields

$$|\kappa(t,s)| \le c \left\{ \begin{array}{ll} 1, & \text{if} \quad \nu < 0 \\ 1+|\ln|t-s||, & \text{if} \quad \nu = 0 \\ |t-s|^{-\nu}, & \text{if} \quad \nu > 0 \end{array} \right.$$

Thus, a kernel (2) is at most weakly singular for $0 \le \nu < 1$. For $\nu < 0$, the kernel (2) is bounded but its derivatives may have diagonal singularities. Most important examples of kernels of type (2) are given by

$$\begin{split} K(t,s) &= g(t,s) |t-s|^{-\nu}, \quad 0 < \nu < 1, \\ K(t,s) &= g(t,s) \ln |t-s|, \end{split}$$

where g is a function which satisfies the condition (A1).

For equations (1) with smooth kernels, the smoothness of the kernel K and the forcing function f determines the smoothness of the solution uon the closed interval [0, b]. If we allow weakly singular kernels of type (2), with smooth coefficient functions $g: [0, b] \times [0, b] \to \mathbb{R}$, then the resulting solutions are typically nonsmooth at the endpoints of the interval of integration [0, b], where their derivatives become unbounded. If g is proposed to be smooth only on $[0, b] \times ([0, b] \setminus \{d\})$, where 0 < d < b, then the derivatives of the solution u(t) of equation (1) may have singularities at t = d, also (see Lemma 1 below). In order to characterize those singularities we introduce a set of functions $C_{d,p}^{m,\nu}[0, b]$.

Let $m \in \mathbb{N}$, $\nu \in \mathbb{R}$, $\nu < 1$, 0 < d < b, $p \in \mathbb{N}_0$, $p \leq m$. Define $C_{d,p}^{m,\nu}[0,b]$ as the collection of continuous functions $u : [0,b] \to \mathbb{R}$ which are m times continuously differentiable in $(0,b) \setminus \{d\}$ and such that the estimate

$$\begin{aligned} \left| u^{(j)}(t) \right| &\leq \\ 1, & \text{if } j < 1 - \nu, \ p \in \{0, 1, \dots, m\}; \\ 1 + \left| \ln t \right| + \left| \ln(b - t) \right|, \\ & \text{if } j = 1 - \nu, \ p \in \{1, \dots, m\}; \\ 1 + \left| \ln t \right| + \left| \ln \left| d - t \right| \right| + \left| \ln(b - t) \right|, \\ & \text{if } j = 1 - \nu, \ p = 0; \\ t^{1 - \nu - j} + (b - t)^{1 - \nu - j}, \\ & \text{if } 1 - \nu < j < 1 - \nu + p, \ p \in \{1, \dots, m\}; \\ t^{1 - \nu - j} + \left| \ln \left| d - t \right| \right| + (b - t)^{1 - \nu - j}, \\ & \text{if } j = 1 - \nu + p, \ p \in \{1, \dots, m - 1\}; \\ t^{1 - \nu - j} + \left| d - t \right|^{1 - \nu - j + p} + (b - t)^{1 - \nu - j}, \\ & \text{if } j > 1 - \nu + p, \ p \in \{0, \dots, m - 1\}, \end{aligned}$$

$$(4)$$

holds with a positive constant c = c(u) for every $t \in (0, b) \setminus \{d\}$ and $j = 1, \ldots, m$.

The following result characterizes the regularity properties of solutions to equation (1), see [4,5].

Lemma 1. Let the conditions (A1) and (A2) about the kernel (2) be fulfilled. Let $f \in C_{d,p}^{m,\nu}[0,b]$, with m,ν,d,p , fixed in the assumptions (A1) and (A2). If the integral equation (1) has an integrable solution $u \in L^1(0,b)$ then $u \in C_{d,p}^{m,\nu}[0,b]$.

3 Piecewise polynomial interpolation

For given $N = 4n, n \in \mathbb{N}, b, d, r, r_d \in \mathbb{R}, 0 < d < b, r, r_d \ge 1$, let

$$\Delta_N = \{t_0, t_1, \dots, t_N : 0 = t_0 < t_1 < \dots < t_N = b\}$$

be a partition (a grid) for the interval [0, b] with the following nodes t_0, \ldots, t_N :

$$t_{j} = \frac{d}{2} \left(\frac{j}{n}\right)^{r}, \ j = 0, 1, \dots, n;$$

$$t_{n+j} = d - \frac{d}{2} \left(\frac{n-j}{n}\right)^{r_{d}}, \ j = 1, \dots, n;$$

$$t_{2n+j} = d + \frac{b-d}{2} \left(\frac{j}{n}\right)^{r_{d}}, \ j = 1, \dots, n;$$

$$t_{3n+j} = b - \frac{b-d}{2} \left(\frac{n-j}{n}\right)^{r}, \ j = 1, \dots, n.$$
(5)

Then Δ_N is called a graded grid for [0, b]. In the present context the so-called grading exponents r, r_d will always satisfy $r \geq 1$ and $r_d \geq 1$. These parameters characterize the accumulation of nodes

 t_0, t_1, \ldots, t_N near the points of possible unboundedness of the derivatives of the solution u of equation (1) (see Lemma 1). For larger r and r_d the grid Δ_N is thicker near 0, d and b. We use two different parameters r and r_d because the order of singularity of the solution u can be different at points 0, band d. If $r = r_d = 1$ then the grid points (5) are uniformly located in the intervals [0, d] and [d, b].

It follows from (5) that an estimate

$$h_N \equiv \max_{j=1,\dots,N} (t_j - t_{j-1}) \le cN^{-1} \tag{6}$$

holds with a positive constant c which is independent of N.

For $m \in \mathbb{N}_0$, let $S_m^{(0)}(\Delta_N)$ and $S_m^{(-1)}(\Delta_N)$ be the spline spaces of piecewise polynomial functions on the grid Δ_N :

$$S_m^{(0)}(\Delta_N) = \left\{ u \in C[0, b] : u \big|_{\sigma_j} \in \pi_m, j = 1, \dots, N \right\},$$

$$S_m^{(-1)}(\Delta_N) = \left\{ u : u \big|_{\sigma_j} \in \pi_m, j = 1, \dots, N \right\}.$$

(7)

In (7) π_m denotes the set of polynomials of degree not exceeding m and $u|_{\sigma_j}$ is the restriction of uto the subinterval $\sigma_j = [t_{j-1}, t_j]$ (j = 1, ..., N). Note that the elements of $S_m^{(-1)}(\Delta_N)$ may have jump discontinuities at the interior grid points t_1, \ldots, t_{N-1} .

In every subinterval $[t_{j-1}, t_j], j = 1, ..., N$ we define $m \in \mathbb{N}$ interpolation points

$$\xi_{j,q} = t_{j-1} + \frac{\eta_q + 1}{2} (t_j - t_{j-1}), \qquad (8)$$

$$q = 1, \dots, m; \ j = 1, \dots, N,$$

where

$$-1 \le \eta_1 < \ldots < \eta_m \le 1 \tag{9}$$

is some fixed system of m parameters on the interval [-1,1], which is the same for every j and N.

To a given continuous function $u : [0, b] \to \mathbb{R}$ we assign a piecewise polynomial interpolation function $P_N u = P_{N,m-1} u \in S_{m-1}^{(-1)}(\Delta_N)$ which interpolates u at the nodes (8). Let $P_N = P_{N,m-1}$: $C[0,b] \to S_{m-1}^{(-1)}(\Delta_N)$ be an interpolation operator which assigns to every continuous function $u : [0,b] \to \mathbb{R}$ its piecewise interpolation function $P_N u$:

$$P_N u \in S_{m-1}^{(-1)}(\Delta_N), \ u \in C[0,b],$$

$$(P_N u)(\xi_{j,q}) = u(\xi_{j,q}), \ q = 1, \dots, m; \ j = 1, \dots, N.$$

(10)

Thus, $(P_N u)(t)$ is independently defined in every subinterval $[t_{j-1}, t_j]$ (j = 1, ..., N) and may be discontinuous at $t = t_j, j = 1, ..., N - 1$; we can treat $P_N u$ as a two-valued function at these points. If $\eta_1 = -1, \eta_m = 1$ then $P_N u$ is a continuous function on the interval [0, b].

Let *E* and *F* be Banach spaces. By $\mathcal{L}(E, F)$ we denote the Banach space of all linear bounded operators $A: E \to F$ with the norm $||A||_{\mathcal{L}(E,F)} =$ $\sup ||Ax||_F$. It follows from [5] that $P_N \in$ $x \in E, ||x||_E \leq 1$ $\mathcal{L}(C[t_{j-1}, t_j], C[t_{j-1}, t_j])$ (j = 1, ..., N) and $P_N \in$ $\mathcal{L}(C[0, b], L^{\infty}(0, b))$. Moreover, the norms of these operators are uniformly bounded in N:

$$\max_{j=1,...,N} \|P_N\|_{\mathcal{L}(C[t_{j-1},t_j],C[t_{j-1},t_j])} \le c, \quad N \in \mathbb{N},$$
$$\|P_N\|_{\mathcal{L}(C[0,b],L^{\infty}(0,b))} \le c, \quad N \in \mathbb{N}.$$
(11)

Here c is a positive constant which is independent of j and N. On the basis of (11) we obtain that

$$||u - P_N u||_{L^{\infty}(0,b)} \to 0 \text{ as } N \to \infty$$
 (12)

for every $u \in C[0, b]$. A consequence of this is

Lemma 2. Let $S : L^{\infty}(0,b) \to C[0,b]$ be a linear compact operator. Then

$$||S - P_N S||_{\mathcal{L}(L^{\infty}(0,b),L^{\infty}(0,b))} \to 0 \text{ as } N \to \infty.$$

In the following we present a result about the rate of the error $||u - P_N u||_{L^{\infty}(0,b)}$.

Lemma 3. Let $u \in C_{d,p}^{m,\nu}[0,b]$, $m \in \mathbb{N}$, $-\infty < \nu < 1$, $p \in \{0, 1, \dots, m\}$. Let the node points (8) with grid points (5) and parameters (9) be used. Let $P_N : C[0,b] \to S_{m-1}^{(-1)}(\Delta_N)$ be determined by the conditions (10).

Then

$$\left\| u - P_N u \right\|_{L^{\infty}(0,b)} \le c \varepsilon_N \,, \tag{13}$$

where c is a positive constant not depending on N and $\varepsilon_N = \varepsilon_N(m, \nu, p, r, r_d)$ is defined as follows:

$$\varepsilon_N = N^{-m},\tag{14}$$

for

$$m < 1 - \nu, \ p \ge 0, \ r \ge 1, \ r_d \ge 1;$$

$$m = 1 - \nu, \ p = 0, \ r > 1, \ r_d > 1;$$

$$m = 1 - \nu, \ p > 0, \ r > 1, \ r_d \ge 1;$$

$$1 - \nu < m < 1 - \nu + p, \ p > 0,$$

$$r \ge \frac{m}{1 - \nu}, \ r_d \ge 1;$$

$$m = 1 - \nu + p, \ p > 0, \ r \ge \frac{m}{1 - \nu}, \ r_d > 1;$$

$$m > 1 - \nu + p, \ p \ge 0,$$

$$r \ge \frac{m}{1 - \nu}, \ r_d \ge 1;$$

$$m > 1 - \nu + p, \ p \ge 0,$$

$$r \ge \frac{m}{1 - \nu}, \ r_d \ge \frac{m}{1 - \nu + p};$$

$$\varepsilon_N = N^{-m} \ln N$$
(15)

for

$$m = 1 - \nu, \ p = 0, \ r = 1, \ r_d \ge 1;$$

$$m = 1 - \nu, \ p = 0, \ r \ge 1, \ r_d = 1;$$

$$m = 1 - \nu, \ p > 0, \ r = 1, \ r_d \ge 1;$$

$$m = 1 - \nu + p, \ p > 0, \ r \ge \frac{m}{1 - \nu}, \ r_d = 1;$$

$$\varepsilon_N = N^{-r(1-\nu)}$$
(16)

for

$$1 - \nu < m < 1 - \nu + p, \ p > 0,$$

$$1 \le r < \frac{m}{1 - \nu}, \ r_d \ge 1;$$

$$m > 1 - \nu + p, \ p \ge 0,$$

$$1 \le r < \frac{m}{1 - \nu}, \ r_d \ge \frac{m}{1 - \nu + p};$$

$$\varepsilon_N = N^{-\min\{r(1 - \nu), r_d(1 - \nu + p)\}}$$
(17)

for

$$m > 1 - \nu + p, \ p \ge 0,$$

 $1 \le r < \frac{m}{1 - \nu}, \ 1 \le r_d < \frac{m}{1 - \nu + p};$
 $\varepsilon_N = N^{-r_d(1 - \nu + p)}$ (18)

for

$$m > 1 - \nu + p, \ p \ge 0,$$

 $r \ge \frac{m}{1 - \nu}, \ 1 \le r_d < \frac{m}{1 - \nu + p}.$

Proof. We follow the approach and techniques of [5]. It follows from (11) that

$$||u - P_N u||_{L^{\infty}(0,b)} \le c \max_{j=1,\dots,N} \max_{t_{j-1} \le t \le t_j} |u(t) - v(t)|,$$

where c is a positive constant not depending on N and v is an arbitrary element of the space $S_{m-1}^{(-1)}(\Delta_N)$. Thus, in order to study the rate of the error $||u - P_N u||_{L^{\infty}(0,b)}$, we have to estimate |u(t) - v(t)| for a suitable v(t) on every subinterval $[t_{j-1}, t_j], j = 1, \ldots, N = 4n$. In particular, taking

$$v(t) = u(t_j) + u'(t_j)(t - t_j) + \frac{1}{2!}u''(t_j)(t - t_j)^2 + \dots + \frac{1}{(m-1)!}u^{(m-1)}(t_j)(t - t_j)^{m-1},$$

where $t \in [t_{j-1}, t_j]$, $j = 1, \ldots, n$, and using (4) for the derivatives of $u \in C_{d,p}^{m,\nu}[0,b]$, we can estimate u(t) - v(t) on the subinterval $[t_{j-1}, t_j] \subset [0, \frac{d}{2}]$, $j = 1, \ldots, n$; in a similar way we can derive the estimates for u - v (with a suitable $v \in S_{m-1}^{(-1)}(\Delta_N)$) on other subintervals $[t_{j-1}, t_j] \subset [\frac{d}{2}, b]$, $j = n + 1, \ldots, 4n$; see [2] for a detailed proof.

4 Collocation method

We look for an approximation u_N to the solution u of equation (1) determing u_N from the following conditions:

$$\begin{bmatrix} u_N(t) - \int_0^b K(t,s)u_N(s)ds - f(t) \end{bmatrix}_{t=\xi_{i,p}} = 0, \\ u_N \in S_{m-1}^{(-1)}(\Delta_N), \quad m \ge 1, \\ p = 1, \dots, m; \ i = 1, \dots, N, \end{cases}$$
(19)

with $\{\xi_{i,p}\}$, given by (8).

Theorem 1. Let the following conditions be fulfilled:

- 1) $K \in C^{1,\nu}_{d,0}[0,b], \ \nu < 1, \ 0 < d < b;$ 2) $f \in C[0,b];$
- 3) the homogeneous integral equation

$$u(t) = \int_{0}^{b} K(t,s)u(s)ds \,, \quad 0 \le t \le b \,, \ (20)$$

has only the trivial solution u = 0;

4) the collocation points (8) with grid points (5) and parameters (9) are used. Then equation (1) has a unique solution $u^* \in C[0, b]$. For all sufficiently large N, say $N \ge N_0$, the collocation conditions (19) determine for every choice of parameters $-1 \le \eta_1 < \ldots < \eta_m \le 1$ a unique approximation $u_N^* \in S_{m-1}^{(-1)}(\Delta_N)$ to u^* and

$$\sup_{t \in [0,b]} |u_N^*(t) - u^*(t)| \to 0 \quad as \quad N \to \infty.$$
 (21)

Proof. We consider equation (1) as the equation

$$u = Tu + f \tag{22}$$

in the Banach space $L^{\infty}(0, b)$, with the operator T, defined by $(Tu)(t) = \int_{0}^{b} K(t,s)u(s)ds$. It follows from the assumtion 1) that T is compact as an operator from $L^{\infty}(0, b)$ to C[0, b] and from $L^{\infty}(0, b)$ to $L^{\infty}(0, b)$, also. Since equation u = Tu has only the trivial solution u = 0, then there exists the inverse operator $(I - T)^{-1} \in \mathcal{L}(L^{\infty}(0, b), L^{\infty}(0, b))$ and equation (22) has a unique solution $u^* =$ $(I - T)^{-1}f \in L^{\infty}(0, b)$. Since $f \in C[0, b]$ and $T \in \mathcal{L}(L^{\infty}(0, b), C[0, b])$, then $u^* \in C[0, b]$.

The collocation conditions (19) can be written in the form

$$u_N = P_N T u_N + P_N f \,, \tag{23}$$

with $P_N: C[0,b] \to S_{m-1}^{(-1)}(\Delta_N)$, defined in Sec. 3. By Lemma 2,

$$\left\| T - P_N T \right\|_{\mathcal{L}(L^{\infty}(0,b),L^{\infty}(0,b))} \to 0 \quad \text{for} \quad N \to \infty.$$
(24)

Using (24) we obtain that $(I - P_N T)$ is invertible for all sufficiently large N, say for $N \ge N_0$, and

$$\|(I - P_N T)^{-1}\|_{\mathcal{L}(L^{\infty}(0,b), L^{\infty}(0,b))} \le c, \quad N \ge N_0,$$
(25)

where c is a positive constant which is independent of N. This shows that for $N \ge N_0$ equation (23) has a unique solution $u_N^* = (I - P_N T)^{-1} P_N f$. We have for it and u^* , the solution of equation (22),

$$(I - P_N T)(u^* - u_N^*) =$$

(I - P_N T)u^* - (I - P_N T)u_N^* = u^* - P_N T u^* - P_N f
= u^* - P_N f - (P_N u^* - P_N f) = u^* - P_N u^*.

Therefore,

$$u^* - u_N^* = (I - P_N T)^{-1} (u^* - P_N u^*).$$

Taking the norms and using (25), we have

$$\left\| u^* - u_N^* \right\|_{L^{\infty}(0,b)} \le c \left\| u^* - P_N u^* \right\|_{L^{\infty}(0,b)}, \ N \ge N_0,$$
(26)

where c is a constant which is independent of N. Since $u^* \in C[0, b]$, the convergence (21) follows from (12) and (26).

Theorem 2. Let the following conditions be fulfilled:

- 1) $K(t,s) = g(t,s)\kappa(t,s)$ is subject to the conditions, stated in the assumptions (A1) and (A2) (see Sec. 2);
- 2) $f \in C^{m,\nu}_{d,p}[0,b]$, with m,ν,d,p , fixed in (A1) and (A2);
- 3) equation (20) has only the trivial solution u = 0;
- 4) the collocation points (8) with grid points (5) and parameters (9) are used.

Then for all sufficiently large N, say $N \ge N_0$, the collocation conditions (19) determine for every choice of parameters $-1 \le \eta_1 < \ldots < \eta_m \le 1$ a unique approximation $u_N^* \in S_{m-1}^{(-1)}(\Delta_N)$ to u^* , the exact solution of equation (1). The following error estimate holds:

$$\sup_{0 \le t \le b} \left| u^*(t) - u^*_N(t) \right| \le c \varepsilon_N \,, \quad N \ge N_0 \,, \quad (27)$$

where c is a positive constant not dependending on N and ε_N is defined by the formulas (14)-(18).

Proof. Due to Theorem 1 we have to prove only the estimate (27). By Lemma 1, $u^* \in C_{d,p}^{m,\nu}[0,b]$. Now the estimate (27) follows from Lemma 3 and the inequality (26).

5 Superconvergence phenomenon

Theorem 2 suggests that by using a collocation method based on piecewise polynomials of degree $m-1 \ (m \ge 1)$ and graded grids of type (5), one can reach a convergence order

$$\sup_{0 \le t \le b} \left| u^*(t) - u^*_N(t) \right| \le c N^{-m}, \quad N \ge N_0, \quad (28)$$

for sufficiently large values of grid parameters r and r_d , see (14)–(18) and (27).

In (28) the order m cannot be improved, whereas piecewise polynomials of the order m-1are used for the approximation. Nevertheless, as it will be seen from Theorem 3 below, the convergence order at the collocation points will be higher than $O(N^{-m})$ for a special choice of collocation parameters (9). Actually, we shall assume that the points (9) are the nodes of a quadrature formula

$$\int_{-1}^{1} g(s)ds = \sum_{k=1}^{m} w_k g(\eta_k) + R_m(g), \qquad (29)$$
$$-1 \le \eta_1 < \dots < \eta_m \le 1,$$

which is exact for all polynomials of degree m.

Note that the weights w_k (k = 1, ..., m) will not be used in our algorithms. The existence of a quadrature formula (29) which is exact for polynomials of degree m is used in the proof of the following

Theorem 3. Let $\nu \in \mathbb{R}$, $\nu < 1$, $m \in \mathbb{N}$, 0 < d < b, $p \in \{0, 1, \dots, m+1\}$. Assume that the following conditions are fulfilled.

(i) The kernel $K(t,s) = g(t,s)\kappa(t,s)$ in equation (1) satisfies the conditions (A1) and (A2) with m + 1 instead of m.

(*ii*)
$$f \in C_{d,p}^{m+1,\nu}[0,b].$$

(iii) The integral equation (20) has only the trivial solution u = 0.

(iv) The collocation points (8) with grid points (5) and parameters (9) are used, where r and r_d are chosen so that if $m < 1 - \nu$, $p \ge 0$, then $r \ge 1$, $r_d \ge 1$; if $m = 1 - \nu$, p = 0, then r > 1, $r_d > 1$; if $m = 1 - \nu$, $p \ge 1$, then r > 1, $r_d \ge 1$; if $1 - \nu + p > m > 1 - \nu$, $p \ge 1$, then $r \ge \frac{m}{1 - \nu}$, $r_d \ge 1$; if $m = 1 - \nu + p$, $p \ge 1$, then $r \ge \frac{m}{1 - \nu}$, $r_d > 1$; if $m > 1 - \nu + p$, $p \ge 0$, then $r \ge \frac{m}{1 - \nu}$, $r_d \ge \frac{m}{1 - \nu + p}$. (v) The quadrature formula (29) is exact for all polynomials of degree m.

Then for all sufficiently large N, say $N \ge N_0$, the collocation conditions (19) determine a unique approximation $u_N^* \in S_{m-1}^{(-1)}(\Delta_N)$ to $u^* \in C[0,b]$, the exact solution of equation (1). For $N \ge N_0$ the following error estimate holds:

$$\max_{q=1,\dots,m;j=1,\dots,N} \left| u_N^*(\xi_{j,q}) - u^*(\xi_{j,q}) \right| \le cN^{-m} \begin{cases} N^{-1}, & \text{if } \nu < 0, \\ N^{-1} \ln N, & \text{if } \nu = 0, \\ N^{-(1-\nu)}, & \text{if } \nu > 0. \end{cases}$$

Here c is a positive constant which is independent of N.

Proof. See [2,3].

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