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#### **Topics**

a) Systems Dynamical systems, Differential Equations: Ordinary Differential Equations
Functional Differential Equations Partial Differential Equations Numerical Methods,
Simulation Nonlinear analysis, Stability, Nonlinear oscillations, Bifurcations, Singular
perturbations Fractals, Ergodic theory, Mathematical Systems Theory, Computational
Intelligence (Neural Nets, Fuzzy Systems, Evolutionary Computing, Ant Colony Optimization
etc...) Artificial Intelligence Knowledge Modelling, Decision Support Systems Hierarchical
Control Systems Stochastic Systems, Non-linear Systems Multidimensional Systems,
Multivariable systems Hybrid Systems, Multirate Systems Speech and Image Processing
Systems Discrete Event Dynamic Systems Manufacturing Systems, Decentralised Systems
Remote Sensing, Microelectromechanical Systems Human-Machine Systems, Image
compression Scientific visualization. Applications and Special Topics

b) Control Mathematical Theory of Control Stability, Observability, Controlability, Factorizability, Reachability Linear Control, Non-Linear Control Optimal Control, Robust Control Computational Intelligence Neural Control, Fuzzy Control, Genetic Control Hybrid (Neural-Fuzzy-Evolutionary) Methodologies Intelligent Control, Stochastic Control, Discrete Control Hierarchical Control, Large Scale Systems, Adaptive Control Predictive Control, Process Control, H-infinity Control Multivariable Control, Multidimensional Control Multivariable Systems, Discrete Event Systems Re-configurable Systems, Real-Time Control Industrial Control, Control for Electric Machines Control for Power Systems, Fault Detection Simulation, Optimization, Identification Estimation, Kalman Filtering, Robotics Robotic Networks, Mechatronics Artificial Intelligence, Circuits, Devices and Systems for Automation and Control Electronics for Control, Electrical and Electronic Measurement Signal Processing for Control, Human-Machine Systems and Cybernetics Modeling and Simulation, Computer Networks for Control Internet Control, Microprocessors, Computer Architecture for Control Software tools for Control, CAD/CAM systems Applications and Special Topics

#### **Articles:**

New Technologies for Nota Fiscal Paulista (Sao Paulo Tax Invoice): Automation of the Tax Documents Issue Process in the Retail of the State of Sao Paulo - Brazil

Authors: Newton Oller De Mello, Marcelo Luiz Alves Fernandez, Vidal Augusto Zapparoli Castro Melo, Eduardo Mario Dias, Caio Fernando Fontana

The Evolution of the Electronic Tax Documents in Latin America

Authors: Eduardo Mario Dias, Newton Oller De Mello, Marcelo Luiz Alves Fernandez

The Neural Network-Based Forecasting in Environmental Systems

Authors: Mihaela Oprea, Alexandra Matei

A Fuzzy Controller with Various T-norms Applied in Robot Navigation

Authors: Ion Iancu , Mihaela Colhon, Mihai Dupac

A New Hardware-Based Actuator for Driving an AC/DC Electromagnetic Contactor

Authors: Chih-Yu Hung, Chieh-Tsung Chi

A Survey on the Application of the Elliptical Trigonometry in Industrial Electronic Systems using Controlled Waveforms with Modeling and Simulating of Two Functions Elliptic Mar and Elliptic Jes-x

Authors: Claude Bayeh

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Authors: Jium-Ming Lin, Po-Kuang Chang

<u>Intelligent System Based on DSP to Monitoring and Maintain Optimum Environmental</u>
<u>Conditions in a Fir Saplings Tree Greenhouse</u>

Authors: Manuela Panoiu, Caius Panoiu, Loredana Ghiorghioni, Raluca Rob

An Automatic Water Management System for Large-Scale Rice Paddy Fields

Authors: Teruji Sekozawa

On-Line Simulator for Decision Support in Distribution Control Centers in a Smart Grid Context

Authors: A. Espinosa-Reza, A. Quintero-Reyes, R.Garcia-Mendoza, J. F. Borjas-Diaz, T. M. Calleros-Torres, B. Sierra-Rodriguez, R. Torres-Abrego

Self – Tuning Control of Continuous – Time Systems

Authors: Marek Kubalcik, Vladimir Bobal

Aircrafts' Control and Command Using Hierarchical Dynamic Inversion

Authors: Mihai Lungu

Modeling of Raw Material Mixing Process in Raw Meal Grinding Installations

Authors: Dimitris Tsamatsoulis

Control System of Unmanned Aerial Vehicle used for Endurance Autonomous Monitoring

Authors: Teodor-Viorel Chelaru, Vasile Nicolae Constantinescu, Adrian Chelaru

Twin Motor Drives in Weapon Systems

Authors: Jiri Balla

<u>Complex Structure Workspace Sweeping Using Semiautonomous Vacuum Cleaners</u>

Authors: Krzysztof Skrzypczyk, Agnieszka Pieronczyk

A Practical Solution for the Classification in Interval-Valued Information Systems

Authors: Amaury Caballero, Kang Yen, Yechang Fang

<u>Mobile Robot Behavior Based Navigation Architecture using a Linear Graph of Passages as</u> Landmarks for Path Definition

Authors: Lubnen Name Moussi, Marconi Kolm Madrid

Design of a Neuro-Controller for Multivariable Nonlinear Time-Varying Systems

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<u>Extended TP Model Transformation for Polytopic Representation of Impedance Model</u> with Feedback Delay

Authors: Peter Galambos, Peter Baranyi, Peter Korondi

Convex Hull Manipulation Based Control Performance Optimisation

Authors: Patricia Grof, Peter Baranyi, Peter Korondi

PSO based Single and Two Interconnected Area Predictive Automatic Generation Control

Authors: Muhammad S. Yousuf, Hussain N. Al-Duwaish, Zakariya M. Al-Hamouz

Takagi-Sugeno vs. Lyapunov-based Tracking Control for a Wheeled Mobile Robot

Authors: Saso Blazic

Wired and Wireless Remote Control of PV System

Authors: Mohamed Zahran, Yousry Atia, Abdullah Alhosseen, Ihab El-Sayed

Synthesis of an Approximate Feedback Nonlinear Control based on Optimization Methods

Authors: Wiem Jebri Jemai, Houssem Jerbi, Mohamed Naceur Abdelkrim

Research Trend on Secure SCADA Network Technology and Methods

Authors: Farkhod Alsiherov, Taihoon Kim

Weather Condition Double Checking in Internet SCADA Environment

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SCADA Architecture with Mobile Remote Components

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A Generalised Minimum Variance Controller for Time-Varying MIMO Linear Systems with

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Stabilization of an Inertia Wheel Pendulum using an Implicit Controller Design

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Pitch Rate Damping of an Aircraft by Fuzzy and Classical PD Controller

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Synchronous Motor Observability Study and a New Robust MRAS Speed Observer with an Improved Zero-speed Position Estimation Design for Surface PMSM

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**Inductive Voltage Transformers Calibration by the Parameters** 

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