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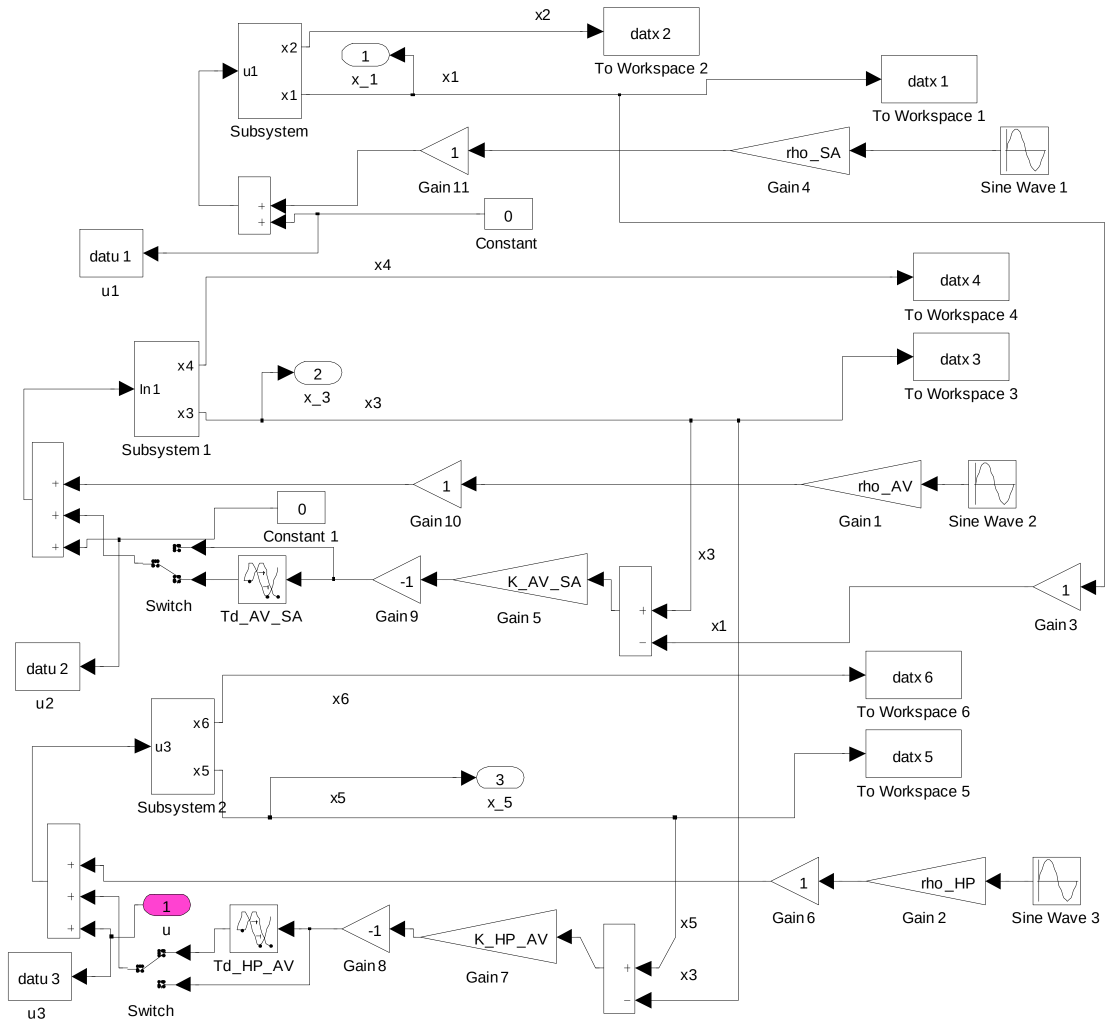

Fig. 12. Simulink implementation of the model corresponding to structure MS1, with signal control u = u_3.