Simulation of the Flicker Phenomenon based on Modeling the Electric Arc

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Abstract: - The Electric Arc Furnace (EAF) is a very large power load, determining the negative effects on the power quality like flicker effect, harmonics currents, and reactive power. These effects are due to the nonlinear characteristic of the electric arc. In this paper is made a study based on simulation about flicker effect caused by Ultra High Power Electric Arc Furnaces (UHP-EAF). For simulation it was use two electric arc models, depending on the nonlinearity of the electric arc. The models are implementing in PSCAD EMTDC simulation program, a program dedicated to power systems. The simulation results are comparing with measurements made in an industrial plant in Romania.

Key-Words: - simulation and modeling, power quality, flicker, harmonics, interharmonics

1. Introduction

The electric arc is a nonlinear element. For study the behavior of the systems based on electric arc it must use techniques to model the nonlinearity of the electric arc. Because the electric arc's nonlinearity, this is a massive generator of harmonic currents and reactive power in electrical power system. The EAF are also a reactive power source because the electric arc is also a reactive load. The electric arc furnace is also and unbalance load. However, one of the most substantial disadvantages of arc furnace is caused by the variations in the line voltage leading to flicker, which can be observed due to the luminosity fluctuation of incandescent lamps. Electric arc furnaces are a main cause of voltage flicker due to the interaction of the high demand currents of the loads with the supply system impedance.

Therefore the main point of analysis focuses on the characteristics of harmonics, and also on the flicker.

The effect of these installations was analyzed using simulation program PSCAD/EMTDC [14]. PSCAD (Power System Computer Aided Design) is a multi-purpose graphical user interface capable of supporting a variety of power system simulation programs. This release supports only EMTDC (Electro-Magnetic Transients in DC Systems).

For simulation it was use an electric arc model, depending on the nonlinearity of the electric arc.

2. Light flicker due to voltage fluctuations

One definition of flicker is "Impression of unsteadiness of visual sensation induced by a light stimulus whose luminance or spectral distribution fluctuates with time" [1]. This means the perception of light flicker is a physiological process. Over the past years numerous studies have been conducted in order to understand the mechanisms behind the flicker phenomenon [15], [16] and [17]. There are at least three different mechanisms influencing the light flicker perception by a human. These are:

- The characteristics of the light source.
- The frequency response of the eye-brain of a human
- The time constant of the eye-brain

Examples of flicker sources

The flicker is in reality a statistical calculation, defined by the EN IEC 61000-4-15 standard and obtained from measuring the rapid variations in voltage. These rapid variations in voltage (figure 1) are, generally speaking, caused by variable loads such as arc furnaces, laser printers, micro-wave ovens or air conditioning systems being started up.

As mentioned in the previous section the main source of severe voltage fluctuations are industrial loads with fluctuating power demands but also wind turbines and wave power etc. can generate flicker. Theoretically, flicker can also be caused by sub- and interharmonic frequency components giving a beating frequency component placed within the flicker frequency spectrum [2], [3] as well as caused by modulation of the voltage harmonics [4]. However, the dominating flicker sources are heavy fluctuating loads like arc furnaces, welding machines, rolling-mills etc.



Figure 1. Rapid variation in voltage.

An arc furnace is probably the load that produces most flicker [5], [6], [7]. When the arc furnace operates, an unstable arc will appear between the electrodes and the scrap resulting in fluctuating power consumption and thereby a potential flicker problem. As a rule of thumb the ratio between the short-circuit capacity at the point of common coupling (PCC) to the maximum demand of the arc furnace should be greater than 80 in order to limit the risk for severe flicker caused by the arc furnace.

The best way to investigate the actual flicker situation is to perform on-site measurements using a flickermeter based on the IEC 61000-4-15 standard.

If the arc furnace is connected to a network with changing loads over time, a good idea is to measure flicker permanently and thereby see the trend of flicker.

Common methods to reduce flicker originating from an arc furnace is to increase the short-circuit level by installing a new main transformer with higher capacity, installing active mitigation equipment like a SVC etc. or to improve the control strategies of the arc furnace. The mitigation methods are quite expensive and discussions between the network operator and the owner of the arc furnace regarding cost sharing are common.

3. Models of the Electric Arc Furnace for flicker simulation

In the specific literature, there are many mathematical models of the electric arc. In [8], [9], [10] and [12] was present some models for the electric arc.

3.1. Model based on the empirical relation between the arc current, arc voltage and arc length

This model are considered by the authors the most appropriate model for describe the electric arc behavior. This model considers the characteristic current-voltage described by relation

$$U_A = U_{th} + \frac{C}{D + I_A}.$$
 (1)

In this relation U_A and I_A are the arc voltage and arc current, and U_{th} are the threshold voltage. The C and D constants determine the difference between the current increasing part and current decreasing part of the current–voltage characteristic (C_a , D_a irrespective C_b , D_b). The typical values ([8], [9], [10], [12]) are: $U_d = 200 \text{ V}$, $C_a = 190000 \text{ W}$, $C_b =$ 39000 W, $D_a = D_b = 5000 \text{ A}$. Because the real values of the model parameters depend on the voltage arc variations, the dynamic arc voltage– current characteristic must be an arc length function, given by relation ([3], [4]):

$$U_A = k \cdot U_{A0}(I_A). \tag{2}$$

In (2) UA0 are the value of the arc voltage for a reference arc length 10 and k is the ratio between the threshold voltage value for arc length 1, Uth(1) and

the threshold voltage value for arc length l_0 , Uth(10).

The dynamic model for electric arc presumes that the relation between the threshold voltage value and the arc length can be expressed by:

$$U_{th} = A + Bl . (3)$$

In (3) A is a constant equal with the sum of cathode and anodic threshold voltages ($A \cong 40V$) and B represent the threshold voltage on the unit length, having usual values of 10V/cm ([9], [12]). The dependency of k by the electric arc length is:

$$k(l) = \frac{A + B \cdot l}{A + B \cdot l_0}.$$
(4)

Using this model, the correction of the electric arc power can be done within loose limits by modifying the threshold voltage, which corresponds in practice to the modification of the distance between the electrodes and the metal bath.

3.2. Modeling the electric arc using the variable-length dynamic characteristic

The quick variations of the voltage absorbed by the electric furnace arc during the melting process are closely dependent on the variations of the electric arc length, caused by the position changing of the metal pieces and the variation of the electrodes positions. At present, two approaches have been developed as to the variation pattern of the electric arc length, the former supposing a determinist approach and the latter, a statistical one.

In this paper it was use the sinus variation of the electric arc length. According to the determinist variation it is considered that the electric arc length has a time-dependent variation pattern that can be described by a sinus law. The time-dependency of anode voltage can be obtained considering that the arc length is changing according to relation

$$l(t) = l_0 - \frac{L}{2} (1 + \sin \alpha t), \qquad (5)$$

where *L* represents the maximal variation of the electric arc length (the electrode movement range) and l_0 is the maximal length of the electric arc (the

maximal distance between the electrode and the metal bath). Using relations (2) - (5) one can obtain the time variation of the dependency $U_A(I_A)$

$$U_A(I_A) = 1 - \frac{B \cdot L/2 \cdot (1 + \sin \omega t)}{A + B \cdot l_0} \cdot U_{A0}(I_A)$$
(6)

By using the notation

$$m = \frac{L}{2l_0 - L},\tag{7}$$

one can notice that for L = 0 we obtain m = 0, and for L = 10 we obtain m = 1, parameter m representing the modulation index of the electric arc length. The model implemented in PSCAD are depicted in figure 2.



Figure 2. The electric arc model for flicker simulation implement in PSCAD EMTDC.

It was obtained, by simulation, the arc voltage waveforms, figure 3. The influence of the modulation index can be observe in fig. 4 where is presented the variation of the arc voltage and the signal spectrum for m=0,2 (red) and for m=0.6 (blue). For the modulation frequency it was choice the value 10 Hz. For this value is most probably to appear flicker phenomena [8]. It can be observed, in figure 3, and 4 that the maximum value of the current envelope corresponds to the minimum value of the voltage magnitude, as result from (2).

By analyze the current and voltage spectrum present in figure 4, it can observe that the voltage spectral characteristic contained the 5th, 7th, 11th, 13th harmonics as is well know in literature but appear components with frequencies different from 50Hz. Therefore, it can be observe 60 Hz, 140Hz and 160 Hz components. The same phenomena appear in the current spectrum.

The magnitude for 5th, 7th, 11th, 13th harmonics and the neighboring interharmonics are show in figure 5. Because by using FFT the frequency step is 2 Hz, in figure 5 are better mark out the interharmonics magnitudes with different frequencies from multiple of modulation frequency.

The influence of modulation index can be analyze from figure 4. It can be observe that form a high value of modulation index (blue), both low frequency harmonics order and interharmonics are significant. For high frequency harmonics order the amplitude of harmonics are more mitigated.

The value of modulation frequency is depending from the distance between harmonics and corresponding harmonic. This distance is increasing with the value of modulation frequency.

The spectral characteristic for the medium voltage line (in the primary of voltage transformer) are show in figure 6. It can be observe the presence of the 5^{th} , 7^{th} , 11^{th} , 13^{th} harmonics and interharmonics. Therefore, the harmonics and interharmonics are transmitted in the medium voltage line.



Figure 3. The waveforms for arc current and voltage m=0.4.



Figure 4. The waveforms for arc voltage and the signals spectrum for m=0.2 (red) and m=0.6 (blue).



Figure 5. The 5th, 7th, 11th, 13th harmonics and the neighboring interharmonics for arc voltage.



Figure 6. The simulated voltage spectral characteristic for medium voltage line feed.

3.3. The model based on the linearization of the electric arc current – voltage characteristic

This model of the AC electric arc used in [8], [10], [11] is based on linearization of the currentvoltage characteristic, typical for the electric arc. Also, this simulation technique is based on the fact that the parameters of the model depend on the power of the charge and therefore the model parameters depend on the work conditions. As the model uses the power absorbed by the electric arc furnace as an input, it results that the model allows the modification of the characteristic currentvoltage, so that the power absorbed can be the prescribe power to be used by the charge circuit.

The principle according to which the model under consideration takes into account the active power absorbed by the circuit is based on the fact that the area of the current-voltage characteristic represents the active power absorbed. The figure 7 presented the typical dynamic characteristic and the linear approximation of the current-voltage characteristic of the AC electric arc and the real dynamic characteristic too.

The leveled approximation of the current-voltage characteristic can be defined in the first quadrant by the equation:

$$u = \begin{cases} i \cdot R_{1} & 0 \le i \le i_{1} \\ i \cdot R_{2} + U_{ig} \cdot \left(1 - \frac{R_{2}}{R_{1}}\right) & i_{1} < i \le i_{2} \end{cases}$$
(8)

where

$$i_1 = \frac{U_{ig}}{R_1},\tag{9}$$

$$i_2 = \frac{U_{dr}}{R_2} - U_{ig} \cdot \left(\frac{1}{R_2} - \frac{1}{R_1}\right)$$
(10)



Figure 7. The linearized and the real dynamic current-voltage cracteristic.

The values i_1 and i_2 correspond to ignition voltage, U_{ig} and drop voltage U_{dr} , of the electric arc and R_1 , R_2 are the tangents of OA and OB segments. For the negative semi period of the arc voltage relation (8) can be prescribed taking into consideration that i_1 and i_2 values are negative. Because the active power is proportionally to the current-voltage characteristic area, the arc resistance on OA segment can be computed using relation (10), where P reprezent the electric arc power.

$$R_{1} = \frac{U_{ig}^{2}}{\left(P + \frac{U_{ig}^{2}}{R_{2}} - \frac{U_{dr}^{2}}{R_{2}}\right)}$$
(11)

To obtain equal values of the arc power on each semiperiod it is necessary to compute the value of parameter R_1 on every semiperiod.

In simulations where used equal values on each semiperiod, $U_{ig}^+ = |U_{ig}^-| = 240 \text{ V}$, for ignition voltage, $U_{dr}^+ = |U_{dr}^-| = 200 \text{ V}$, for drop voltage. The R_2 value was choose based on data literature [8], [10], [11] $R_2 = -0,0007272$. The value of R_1 is computed using relation (10), the electric power value been choose P = 25,4 MW.

In [10] was detailed present the PSCAD-EMTDC electrical scheme of the installation of the electric arc furnace based on this model. It was show the implementation of the model only for one phase of the three phase electric arc because for the other two phases the model implementations are identically. In [10] was also present the waveform of the arc current and voltage obtained by simulation and the dynamic current – voltage characteristic of the electric arc, for simulated data.

For the simulation of the flicker phenomenon, it was necessary to obtain the variation of the electric arc characteristic, and this was realized by imposing a variation to a parameter of the model. Some parameters are conditioned by it. The variable chosen parameter is R_1 . Taking into consideration that the ignition voltage, drop voltage and the power of the electric arc are constants, using the (11) relation, it can be computed in every moment the value of R_2 . In this way, the current-voltage characteristic of the electric is variable, and its variation depends on the R_1 parameter variation law. For an accurate implementation of this model, the following conditions must be accomplished:

- During the implementation of the dynamic model is necessary to ensure constantly the value of the R_1 parameter for at least a semi-period of the supply voltage. This demand must be accomplished for realizing of the current-voltage characteristic for any value of the simulated current and voltage, considering as reference the same time interval.

- The variation of the R_1 parameter in every semiperiod of the supply voltage ensures the unsymmetrical current and voltage of the electric arc, a characteristic of the electric arc furnace.
- The variation law of the R_1 parameter has to ensure constant of its medium value in order to maintain constant the power of the electric arc

There were developed two landing directions for the R1 parameter variation: a determinist landing and statistical landing.

3.3.1. The sinusoidal variation of the R_1 parameter

The determinist landing presumes that the R_1 parameter describes a sinusoidal curve. The time dependence of the R_1 parameter can be obtain taking into consideration that is has variation according to the relation:

$$R_{1}(t) = R_{1} \cdot (1 + m \cdot \sin 2\pi f_{0}t)$$
(12)

where f_0 is the variation frequency of the R_1 parameter, and m is the modulation index. For the simulation of the flicker phenomenon, f_0 has a value in the frequency domain where this phenomenon is developing.

From (12) relation it can be observed that the medium value of the $R_1(t)$ parameter is equal to R_I , so the medium power of the electric arc is constant. The simulation scheme implemented in PSCAD EMTDC are depicted in figure 9. The simulations are permitting to obtain the wave forms of the current and the voltage of the electric arc, and the value of the R_I parameter presented in figure 8. In these simulations, the modulation frequency is 10Hz, and the modulation index is m=0,8.

3.3.2. The random variation of the R₁ parameter

The statistic landing presumes that the variation of the R_1 parameter is described by a band limited white noise law. In this case the time dependence of the R_1 parameter can be obtained according the relation:

$$R_1(t) = R_1 + r(t)$$
(13)

where r(t) represents a zero media white noise and a limited frequency band signal. Like in the preceding cases, the frequency band is chosen in the frequency domain where the flicker phenomenon is developing. The figure 10 represents the current and the voltage of the electric arc variation form and the variation of the R₁ parameter using the modulation index m=0,6.



Figure 8. The model implement in PSCAD EMTDC for sinusoidal variation of the parameter R₁.



Figure 9. The waveforms for arc voltage and the signals spectrum for m=0.8.



Figure 10. The waveforms for arc voltage and the signals spectrum for m=0.6.

4. Comparison with measurements items

The measurements were made at a 3-phase power supply installation of a 3-phase EAF of 100t, to which were not connected the harmonics filters.

The measurements were made using a numerical data acquisition board. Details about the measurements method are present in [13].

In figure 10 are show the signal spectrum for simulated voltage in secondary of transformer and in figures 11 and 12 are show the signal spectrum for measured voltage in secondary and in primary of transformer (for one phase).

Comparing the simulating spectral characteristic from figure 4 and figure 6, and measured spectrum from figure 11 and figure 12 (for the medium voltage line feed) it can be observe the presence of the same harmonics and interharmonics.

5 Conclusion

The functioning of electric arc furnace can cause power quality problems, especially as voltage flickers, to the power supply system to which it is connected. Nowadays, most utilities and power customers are facing the need to solve the power quality problem created by EAF. In this paper the possibility of flicker simulation was analyze using a dedicated simulation program. For simulation it was use two models of the electric arc. Both these models allow simulating the rapid variation of the electric arc parameters. The results of simulation were comparing with some measurements made on an industrial plant. By compare the simulation with the measurements results that the models are appropriate to study the flicker phenomena and the nonsinusoidal regime.



Figure 11. The voltage spectral characteristic for measure voltage in the secondary voltage transformer.



Figure 12. The voltage spectral characteristic for measure voltage in the primary voltage transformer.

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