Knowledge Induction from Medical Databases with Higher-Order Programming

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Abstract: - Medical data mining is an emerging area of computational intelligence applied to automatically analyze patients' records aiming at the discovery of new knowledge potentially useful for medical decision making. Induced knowledge is anticipated not only to increase accurate diagnosis and successful disease treatment, but also to enhance safety by reducing medication-related errors. Modern healthcare organizations regularly generate huge amount of electronic data that could be used as a valuable resource for knowledge induction to support decision-making of medical practitioners. Unfortunately, a domain-specific decision support system that provides a suite of customized and flexible tools to efficiently induce knowledge from medical databases with representational heterogeneity does not currently exist. We, thus, design and develop a medical decision support system based on a powerful logic programming framework. The proposed system includes a knowledge induction component to induce knowledge from clinical data repositories and the induced knowledge can also be deployed to pre-treatment data from other sources. The implementation of knowledge induction engine has been presented to express the power of higher-order programming of logic-based language. The flexibility of our mining engine is obtained through the pattern matching and meta-programming facilities provided by logic-based language.

Key-Words: - Medical decision making, Medical informatics, Logic-based knowledge induction, Higher-order programming

1 Introduction

Knowledge is a valuable asset to most organizations as a substantial source to enhance understanding of data relationships and support better decisions to increase organizational competency. Automatic knowledge acquisition can be achieved through the availability of the knowledge induction component. The induced knowledge can facilitate various knowledge-related activities ranging from expert decision support, data exploration and explanation, estimation of future trends, and prediction of future outcomes based on present data.

In this paper, we present the knowledge induction system specifically designed to facilitate knowledge discovery from medical data. Various data mining and machine learning methods had been proposed to learn useful knowledge from medical data [5], [6], [7], [8], [17], [19]. Major techniques adopted by many researchers are rule induction and classification tree generation with the main purpose to support medical diagnosis [3], [9], [13]. Some researchers had even extended the knowledge discovery aspect to the larger scale of medical decision support system and data warehouse [2], [4], [10], [11], [20].

Our work is also in the main stream of medical decision support system development, but our methodology is different from those appeared in the literature. The system proposed in this paper is based on logic and higher-order programming paradigms. The justification of our logic-based system is that the closed form of Horn clauses that treats program in the same way as data facilitates fusion of knowledge learned from different sources; this situation is a normal setting in medical domain. Knowledge reuse can also easily practice in this framework. We design the system as an integrated environment storing a repertoire of tools for discovering various kinds of knowledge.

The outline of this paper is as follows. Section 2 briefly discusses knowledge induction methods implemented in our system. Section 3 reviews the basics of logic and higher-order programming. Sections 4 and 5 present the conceptual design and implementation, respectively, of our system. Section 6 concludes the paper.

2 Knowledge Induction Methods

This section briefly reviews the three main data mining methods extensively applied to induce knowledge from varieties of data domains. These methods are implemented in our medical decision support system.

2.1 Tree-Based Knowledge Induction

Decision tree induction [18] is a popular method for inducing knowledge from data. Popularity is due to the fact that mining result in a form of decision tree is interpretability, which is more concern among medical practitioners than a sophisticated method but lack of understandability. A decision tree is a hierarchical structure with each node contains decision attribute and node branches corresponding to different attribute values of the decision node. The goal of building decision tree is to partition data with mixing classes down the tree until the leaf nodes contain pure class.

In order to build a decision tree, we need to choose the best attribute that contributes the most towards partitioning data to the purity groups. The metric to measure attribute's ability to partition data into pure class is *Info*, which is the number of bits required to encode a data mixture. To choose the best attribute, we have to calculate information gain, which is the yield we obtained from choosing that attribute. The information gain calculates yield on data set before splitting and after choosing attribute with two or more splits. The gain value of each candidate attribute is calculated. Then choose the maximum one to be the decision node. The process of data partitioning continues until the data subset has the same class label.

2.2 Association Mining

Association mining is the discovery of relationships or correlations between items in a database. Let I = $\{i_1, i_2, i_3, ..., i_m\}$ be a set of *m* items and $DB = \{C_1, C_2, C_3, ..., C_n\}$ be a database of *n* cases or observations and each case contains items in *I*. A *pattern* is a set of items that occur in a case. The number of items in a pattern is called the length of the pattern. To search for all valid patterns of length 1 up to *m* in large database is computational expensive. For a set *I* of *m* different items, the search space for all distinct patterns can be as huge as 2^m -1. To reduce the size of the search space, the *support* measurement has been introduced [1]. The function *support*(*P*) of a pattern *P* is defined as a number of cases in DB containing *P*. Thus, $support(P) = |\{T \mid T \in DB, P \subseteq T\}|$. A pattern *P* is called *frequent pattern* if the support value of *P* is not less than a predefined minimum support threshold *minS*. It is the *minS* constraints that help reducing the computational complexity of frequent pattern generation. The *minS* metric has an antimonotone property and is applied as a basis for reducing search space of mining frequent patterns in algorithm Apriori [1].

2.3 Data Clustering

Clustering refers to the iterative process of automatic grouping of data based on their similarity. There exist a large number of clustering techniques, but the most classical and popular one is the k-means algorithm [12]. Given a data set containing n objects, k-means partitions these objects into k groups. Each group is represented by the centroid, or central point, of the cluster. Once cluster means or representatives are selected, data objects are assigned to the nearest centers. The algorithm iteratively selects new better representatives and reassigns data objects until the stable condition has been reached. The stable condition can be observed from cluster assigning that each data object does not change its cluster.

3 Programming Based on Logic

In logic programming, a clause is a disjunction of literals (atomic symbols or their negations) such as $p \lor q$ and $\neg p \lor r$. A statement is in clausal form if it is a conjunction of clauses such as $(p \lor q) \land (\neg p \lor r)$. Logic programming is a subset of first order logic in which clauses are restricted to Horn clauses.

A Horn clause, named after the logician Alfred Horn [16], is a clause that contains at most one positive literal such as $\neg p \lor \neg q \lor r$. Horn clauses are widely used in logic programming because their satisfiability property can be solved by resolution algorithm (an inference method for checking whether the formula can be evaluated to true).

A Horn clause with no positive literal, such as $\neg p \lor \neg q$, which is equivalent to $\neg (p \land q)$, is called *query* in Prolog and can be interpreted as ':- p, q' in which its value (true/false) to be proven by resolution method. A clause that contains exactly one positive literal such as r is called a *fact* representing a true statement, written in clausal form as 'r :-' in which the condition part is empty and that means r is unconditionally true. Therefore, facts are used to represent data. A Horn clause that contains one positive literal and one or more

negative literals such as $\neg p \lor \neg q \lor r$ is called a *definite clause* and such clause can equivalently written as $(p \land q) \rightarrow r$ which in turn can be represented as a Prolog *rule* as r := p, q. The symbol ':-' is intended to mean ' \leftarrow ', which is implication in first-order logic (it stands for 'if'), and the symbol ',' represents the operator \land (or 'AND').

In Prolog, rules are used to define procedures and a Prolog program is normally composed of facts and rules. Running a Prolog program is nothing more than posing queries to obtain true/false answers. The advantages of using logic programming are the flexible form of query posing and the additional information regarding variable instantiation obtained from the Prolog system once the query is evaluated to be true.

The symbols p, q, r are called *predicates* in firstorder logic programming and they can be quantified over variables such as r(X) := p(X,Y), q(Y). This clause has the same meaning as $\forall X (p(X,Y) \land q(Y) \rightarrow r(X))$. The scope of variables is within a clause (delimit the end of clause with a period). Horn clauses are thus the fundamental concept of logic programming.

Higher-order predicate is a predicate in a clause that can quantify over other predicate symbols [14], [15]. As an example, besides the rule r(X):- p(X,Y), q(Y), if we are also given the following five Horn clauses (or facts): p(1, 2). p(1, 3). p(5, 4). q(2). q(4).

By asking the query: ?- r(X), we will get the response as '*true*' and also the first instantiation information as X=1. If we want to know all instantiations that make r(X) to be true, we may ask the query: ?- *findall(X, r(X), Answer)*.We will get the response: *Answer* = [1,5], which is a set of all answers obtained from the predicate r(X) according to the given facts. The predicate symbol *findall* quantifies over the variables *X, Answer*, and the predicate *r*. The predicate *findall* is thus called a higher-order predicate.

Meta-level programming is also another powerful feature of Prolog. Meta-programs treat other programs as their input data. Data and program in Prolog take the same representational format, i.e. clausal form. Therefore, it is very natural to write meta-program in Prolog.

The following example illustrates the procedure *map* that takes a list of integers [1,2,3,4,5] and another procedure *square* as its input arguments and produce a list of square values as its output. If we pose the query: ?- *map*(*square*, [1,2,3,4,5], L), then we will get the answer: L = [1,4,9,16,25].

square(X, Y) := Y is X * X.

map(ProcedureName, [H/T], [NewH/NewT]) :-

Procedure=.. [ProcedureName,H,NewH], call(Procedure), map(ProcedureName, T, NewT).

map(_, [], []).

4 Medical Decision Support System

Health information is normally distributive and heterogeneous. Hence, we design the medical decision support system (Figure 1) to include data integration component at the top level to collect data from distributed databases and also from documents in text format. Data at this stage are to be stored in a warehouse to support direct querying as well as analysis with knowledge induction engine.

Knowledge base in our design stores both induced knowledge, in which its significance has to be evaluated by the domain expert, and background knowledge encoded from consultation with human experts. Knowledge inferring and reasoning is the module interfacing with medical practitioners and physicians at the front-end and accessing knowledge base at the back-end.

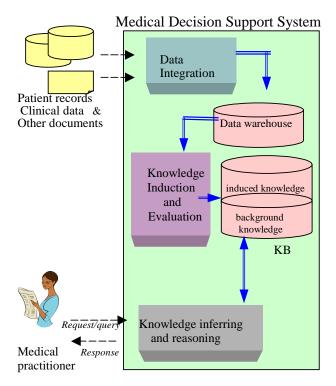


Figure 1. Knowledge induction component in the medical decision support system

The process of knowledge discovery is complex and iterative in its nature. We design the system to be composed of two phases: knowledge induction and knowledge inferring.

Knowledge induction is the back-end of the system responsible for acquiring and discovering new and useful knowledge. Usefulness is to be validated at the final step by human experts. Discovered knowledge is stored in the knowledge base to be applied to solve new cases or create new knowledge in the knowledge inferring phase, which is the front-end of the proposed system.

The proposed system obtains input from heterogeneous data sources. Such data can be redundant, incomplete, and noisy. Therefore, the knowledge-induction-and-evaluation component (Figure 2) has been designed to clean, transform, and select only relevant data sample.

Knowledge-induction-and-evaluation

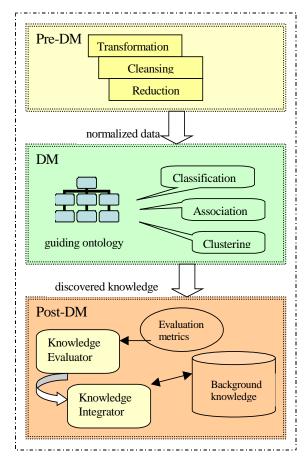


Figure 2. Architecture of the knowledge-inductionand-evaluation component

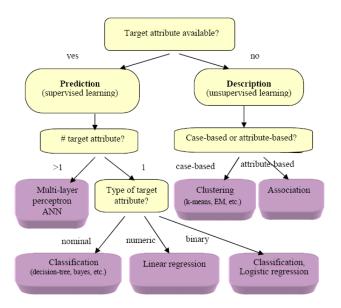


Figure 3. Ontology for guiding mining-method selection at the DM step

The DM component is for performing various mining tasks. Currently, we design and implement three different mining modules, i.e. classification, association, and clustering. We adopt the ontology concept at this step to guide the mining methodology selection. A simple form of ontology to select appropriate mining method is shown in Figure 3.

The Post-DM component composed of two main features: knowledge evaluator and knowledge integrator. These features perform functionalities aiming at a feasible knowledge deployment. Knowledge evaluator involves evaluation, based on corresponding measurement metrics, of the mining results. Knowledge integrator examines the induced patterns to remove redundant knowledge.

5 System Implementation

In this section, we present the Prolog coding of DM, a major module for mining different kinds of knowledge in the knowledge-induction-and evaluation component. Prolog code is based on the syntax of SWI Prolog (www.swi-prolog.org).

Data format. The data to be used by any mining method of the DM module take the same format, that is, as a Prolog file. As an illustration, we use the allergy data of ten patients. The following data show information of ten patients suffering from allergy (class = yes). The possible indicative symptoms are sore throat, fever, swollen glands, congestion, and

headache. Some patients had some of these symptoms but are not suffering from allergy (class = no). To induce the common symptoms (or model) of allergy patients from this data, we have to save this data set as a Prolog file (data.pl).

%% Data: Allergy diagnosis

% Patients' symptoms and their possible values attribute(soreThroat, [yes, no]).

attribute(fever, [yes, no]).

attribute(swollenGlands, [yes, no]).

attribute(congestion, [yes, no]).

attribute(headache, [yes, no]).

attribute(class, [yes, no]).

% data instances

- instance(1, class=no, [soreThroat=yes, fever=yes, swollenGlands=yes, congestion=yes, headache=yes]).
- instance(2, class=yes, [soreThroat=no, fever=no, swollenGlands=no, congestion=yes, headache=yes]).

- instance(5, class=no, [soreThroat=no, fever=yes, swollenGlands=no, congestion=yes, headache=no]).

instance(7, class=no, [soreThroat=no, fever=no, swollenGlands=yes, congestion=no, headache=no]).

instance(8, class=yes, [soreThroat=yes, fever=no, swollenGlands=no, congestion=yes, headache=yes]).

instance(9, class=no, [soreThroat=no, fever=yes, swollenGlands=no, congestion=yes, headache=yes]).

instance(10, class=no, [soreThroat=yes, fever=yes, swollenGlands=no, congestion=yes, headache=yes]). **Classification.** The objective of classification is to induce data model of two classes: positive (class = yes) and negative (class=no). Binary classification is a typical task in medical data mining. The code, however, can be easily modified to classify data with more than two classes. To induce the common symptoms (or model) of patients suffering from allergy, we use the decision-tree induction method [18]. The process starts when the following main module is invoked. Note that clauses containing higher-order predicates are highlighted throughout the given program code.

:-include('data.pl').
:-dynamic current_node/1,node/2,edge/3.

main :-

init(AllAttr,EdgeList), getNode(N), % get node number create_edge(N,AllAttr,EdgeList), print_model.

init(AllAttr,[root-nil/PB-NB]) : retractall(node(_,_)),
 retractall(current_node(_)),
 retractall(edge(_,_,_)),
 assert(current_node(0)) ,
 findall(X, attribute(X,_), AllAttr1),
 delete(AllAttr1, class, AllAttr),
 findall(X2,instance(X2,class=yes,_),PB),
 findall(X3,instance(X3,class=no,_),NB).

getNode(X) : current_node(X),

X1 is X+1, retractall(current_node(_)), assert(current_node(X1)).

The main module calls the *init* procedure (or precidate) to initialize the temporary knowledge base by removing all information that might be remained in the knowledge base and asserting the root node of the tree. The node and edge structures of our decision tree have the following formats:

node(nodeID, [PositiveCase]-[NegativeCase])

edge(ParentNode, EdgeLabel, ChildNode)

The node structure is composed of two parts: node-id and the mixture of positive and negative cases in that node. The edge is a link from parent node to child node. Each edge contains three pieces of information; that is, id of parent node, the edge label, and id of child node. Node id 0 is a special node representing a root node and it links to node number 1. The tree building starts with the *create_edge* and *create_nodes* procedures.

```
create_edge(_,_,[]) :- !.
create_edge(_,[],_) :- !.
create_edge(N, AllAttr, EdgeList) :-
        create nodes(N, AllAttr, EdgeList).
create_nodes(_,_,[]) :- !.
create_nodes(_,[],_) :- !.
create_nodes(N, AllAttr, [H1-H2/PB-NB|T]) :-
      getNode(N1), % get node number N1
      assert(edge(N,H1-H2,N1)),
      assert(node(N1,PB-NB)),
      append(PB, NB, AllInst),
      ( (PB \== [], NB \== []) ->
        (cand_node(AllAttr, AllInst, AllSplit),
         best attribute(AllSplit,
                      [V, MinAttr, Split]),
         delete(AllAttr, MinAttr, Attr2),
         create_edge( N1, Attr2, Split))
         ; true).
       create_nodes(N, AllAttr, T).
best attribute([], Min, Min).
best_attribute([H | T], Min) :-
      best_attribute(T, H, Min).
best attribute([H | T], Min0, Min) :-
```

H =[V,_, _], Min0 = [V0, _, _], (V < V0 -> Min1 = H; Min1 = Min0), best_attribute(T, Min1, Min).

% generate candidate decision node cand_node([],_,[]) :- !. cand_node(_,[],[]). cand_node([H | T],Ins,[[Val,H,SplitL] | Att]) :info(H, Ins, Val, SplitL),
cand_node(T,Ins,Att).

% compute Info of each candidate node concat3(A,B,C,R) :atom_concat(A,B,R1), atom_concat(R1,C,R). info(A, CurInstL, R, Split) :attribute(A,L), **maplist(concat3(A,=), L, L1),** suminfo(L1, CurInstL, R, Split).

suminfo([],_,0,[]). suminfo([H | T], CurInstL, R, [Split | ST]) :-AllBag=CurInstL, term_to_atom(H1,H), findall(X1, (instance(X1,_,L1), member(X1, CurInstL), member(H1,L1)), BagGro), findall(X2,(instance(X2,class=yes, L2), member(X2, CurInstL), member(H1,L2)), BagPos), findall(X3,(instance(X3,class=no, L3), member(X3, CurInstL), member(H1,L3)), BagNeg), (H11=H22) =H1, length(AllBag, Nall), length(BagGro, NGro), length(BagPos, NPos), length(BagNeg, NNeg), Split = H11-H22/BagPos-BagNeg, suminfo(T, CurInstL, R1,ST), (NPos is 0 * -> L1 = 0;L1 is (log(NPos/NGro)/log(2))), $(0 \text{ is NNeg }^{*} - 2 = 0;$ L2 is (log(NNeg/NGro)/log(2))), (NGro is 0 -> R= 999; R is (NGro/Nall)*(-(NPos/NGro)*L1-(NNeg/NGro)*L2)+R1).

The given source code does not provide detail for *print_model* procedure. Interested readers are suggested to simply add a rule *print_model :- true*.

Then run the program by calling predicate *main*. Prolog will respond *true* with no other information because we simply add the always-true condition in the *print_model* predicate. At this moment we can view the tree model by calling *listing(node)* and *listing(edge)* predicates. The results will be as follows:

1 ?- main. true.

2 ?- listing(node).

:- dynamic user:node/2. user:node(1, [2, 6, 8]-[1, 3, 4, 5, 7, 9, 10]). user:node(2, []-[1, 3, 5, 9, 10]). user:node(3, [2, 6, 8]-[4, 7]). user:node(4, []-[4, 7]). user:node(5, [2, 6, 8]-[]).

true.

3 ?- listing(edge).

:- dynamic user:edge/3. user:edge(0, root-nil, 1). user:edge(1, fever-yes, 2). user:edge(1, fever-no, 3). user:edge(3, swollenGlands-yes, 4). user:edge(3, swollenGlands-no, 5). true.

The running results convey the following information. From node number 1, the edge with label fever-yes (representing attribute fever with a value yes) links to node number 2. Node 1 contains all ten cases of patients suffering and not suffering from allergy, whereas node 2 contains the information []-[1,3,5,9,10] to infer none of positive cases and five negative cases. Therefore, the results in the above node and edge structures represent the following data model:

class(allergy) :- fever=no, swollenGlands=no.

Association mining. We implement the association mining module based on the algorithm APRIORI [1]. The implementation shows only the first pass of the algorithm; that is, the generation of frequent itemsets. The second pass, which is the generation of association rules from frequent

itemsets, can be easily extended from the given code.

Main predicate of this module is association_mining. Upon invocation, this predicate obtains input data from the predicate input(Data), and get the minimum support value through the predicate *min_support(V)*. Then the main predicate starts the process by making candidate and large itemsets of length one, two, three, and so on (through the predicates makeC1, makeL, and apriori_loop, respectively). All highlighted terms are higher-order predicates. These predicates are maplist, include, and setof.

The predicate *maplist* takes three arguments; therefore, it may be written as *maplist/3*. This predicate applies its first argument, which is also a predicate, to each element of a list appeared in the second argument. The result is a list in the third argument.

The predicate *include/3* takes another predicate as its first argument and adds the result obtained from the first argument to the list in second argument. The result appears as a list in the third argument. The predicate *setof/3* also works with other predicate to collect each answer as a list in its third argument.

association_mining : input(Data),
 min_support(V),
 makeC1(C),
 makeL(C,L),
 apriori loop(L,1).

apriori_loop(L,N) :length(L) is 1,!. apriori_loop(L,N) :- N1 is N+1, makeC(N1,L,C), makeL(C, Res), apriori_loop(Res, N1).

makeC1(Ans) :- input(D), allComb(1, ItemSet, Ans2), maplist(countSS(D), Ans2, Ans).

 maplist(list_to_ord_set, Ans2, Ans3) ,
list_to_set(Ans3,Ans4),
include(len(N), Ans4, Ans5),
maplist(countSS(D), Ans5, Ans).

%scan database to find: List+N makeL(C,Res) :- include(filter, C, Ans), maplist(head, Ans, Res).

filter(_+N) :- input(A), length(A, I), min_support(V), N>=(V/100)*I.

 $head(H+_,H).$

% arbitrary subset of the set containing % given number of elements comb(0, _, []). comb(N, [X | T], [X | Comb]) :-N > 0, N1 is N-1, comb(N1,T,Comb). comb(N,[_|T],Comb) :-N > 0, comb(N,T,Comb).

allComb(N,I,Ans) :setof(L, comb(N, I, L), Ans).

countSubset(A,[],0).

 $\begin{array}{l} countSubset(A, [B\,|\,X], N):\\ not(subset(A, B)),\\ countSubset(A, X, N). \end{array}$

countSubset(A,[B|X],N) : subset(A,B),
 countSubset(A,X,N1),
 N is N1+1.

countSS(SL,S,S+N) : countSubset(S,SL,N).
len(N,X) :- length(X,N1), N is N1.

Clustering. We implement the data clustering based on k-means algorithm [12]. The main predicate is *clustering* in which the number of clusters (k) has to be specified and data are to be included. The predicate *makeInitCluster* creates initial k clusters with randomized k centroids, then assign each data to the closest centroid through the predicate *assignPoint*.

Note that the symbol '*', such as those appear in the predicate cmax(Res, A*V) and freq(X, N*Y, N*F), refers to the data format to represent *Attribute*Value*; it does not mean multiplication. In Prolog, numerical computation will occur in a clause with the predicate '*is*', such as *S1 is S + 1* in the *reComputeCenter* procedure.

The iteration step, *repeatCompute* predicate, recomputes the new k centroids and then re-assign each data point to the new closest centroid. Iteration stops when all data do not change their clusters. The source code presented in the following works with categorical data. For numerical or data with mixing types, the distance measurement has to be modified.

clustering(K) :-

makeInitCluster(K, AllClust), assignPoint(AllClust, Data, Start, AllPt), OldClust=AllClust, repeatCompute(K, AllPt, OldClust).

makeInitCluster(K, AllClust):initClust(K, 1, AllClust).

initClust(K, L0, []) :-L0 > K , ! . initClust(K, L0, [L0*L|T]) :instance(L0,_,L), L1 is L0+1, initClust(K, L1, T).

assignPoint(_, U, M, []) :-M > U, !. assignPoint(AllClust, U, M, [M-V-A | T]) :maplist(freq(M), AllClust, Res), cmax(Res, A*V), M1 is M+1, assignPoint(AllClust, U, M1, T). freq(X, N*Y, N*F) : instance(X, _, L1),
 intersection(L1, Y, I),
 length(I, F).

cmax(L, A*V) : **maplist(cvalue, L, L2),** max_list(L2, V), member(A*V, L), !.

cvalue(_*V, V).

$$\label{eq:computedenter} \begin{split} \text{reComputeCenter}(\text{K, S, AllPoint, []}) &:\\ & \text{S} > \text{K}, ~!. \end{split}$$

reComputeCenter(K, S, AllPoint, [S*NewC|T]) :findall(P, member(P-_-S, AllPoint), Z),
allPointAtAllAttr(Z, NewC),

S1 is S+1, reComputeCenter(K, S1, AllPoint, T).

allPointAtAllAttr(AllP, NewClusters) :findall(AttName, (attribute(AttName,_), AttName\==class), AttNameL), maplist(allPoint(AllP), AttNameL, NewClusters).

allPoint(AllP, Att, A) :findall(Att=V, (instance(X, _, K), member(X, AllP), member(Att=V, K)), Z), maxFreq(Z, A*V).

maxFreq(L, A*V) :findall(X*C, (member(X,L), count(X,L,C)), Z),
cmax(Z,A*V).

repeatCompute(K, AllPt, OldClust) : reComputeCenter(K,Start,AllPt,NewClus),
 (OldClust==NewClus ->
 writeln('-No-cluster-changes***End*');
 (writeln(newClust-NewClus),
 assignPoint(NewClus,Data,Start,AllPt2),
 writeln(allNewPoint-AllPt2),
 repeatCompute(K, AllPt2, NewClus))).

6 Conclusion

Huge amount of data collected by hospitals and clinics are not yet turned into useful knowledge due to the lack of efficient analysis tools. We thus propose a rapid prototyping of an automatic datamining tool to induce knowledge from medical data. The induced knowledge is to be evaluated and integrated into the knowledge base of a medical decision support system. Discovered knowledge facilitates the reuse of knowledge base among decision-support applications within organizations that own heterogeneous clinical and health databases. One obvious application of such knowledge is to pre-process other data sets by grouping it into focused subset containing only relevant data instances.

Our implementation of knowledge induction engines is based on the concept of higher-order Horn clauses using the logic-programming paradigm. Higher-order programming has been originally appeared in functional languages and soon be ubiquitous in several modern programming languages such as Java. Higher order style of programming has shown the outstanding benefits of code reuse and high level of abstraction.

This paper illustrates higher order programming techniques in Prolog by means of higher-order predicates such as *maplist*, *findall*, *setoff*, and *include*. These predicates take other predicates as its argument. With such expressive power of higherorder predicates, program coding of the designed system is very concise as demonstrated in the paper. Program conciseness contributes directly to program verification and validation, which are important issues in software engineering.

The powerful feature of meta-level programming in Prolog facilitates the reuse of data-mining results represented as rules to be flexibly applied as conditional clauses in other applications. The plausible extension of our current work is to add constraints into the knowledge induction method in order to limit the search space and therefore yield useful and timely knowledge. We also plan to extend our system to work with stream data that normally occur in modern medical institutions.

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