

Modeling of the Microflow Sensor

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Abstract: - The problem of accurate determination of micro mass flow was studied. The measurement of mentioned flow range is becoming more and more important for a lot of applications in the life science, analysis, biotechnologies, synthesis and nanotechnology markets. In this paper a flowmeter design applicable for measurement of low gas flow amounts is presented. To this end, the numeric model of designed flowmeter was made and the flowmeter was numerically simulated using compressible Navier – Stokes equations in two dimensions. The computations were carried out for several types of agitated gases. The results were compared with experimental data.

Key-Words: - modeling, flow, sensor, model, gas, flowmeter

1 Introduction

This work is focused on the modelling of a thermal method for mass flow determination of flowing media. The modelling of microsystems requires appropriate compact or macro models for microdevices. In general, it is difficult or almost impossible to obtain closed form analytical models for microdevices. Thus, models are obtained by a simplification of the full physical model. The compact models allow for fast system level simulation of the microsystem. However, the accuracy of such a model can be questionable because of the simplifications made during the model development phase. Model accuracy and simplicity are important for the design of complex systems. Microflow sensor modelling has been examined by several authors [1]. These approaches have used a solution of the partial differential equations (PDEs) for the coupled fluid/thermal problem. The work of [2] employs equivalent circuit descriptions that are solved in SPICE whereas [3] solve the PDEs using the finite-element and the finite-difference methods, respectively. However, none of these methods provide a simple and accurate macromodel for the flow sensor.

In this paper is presented modelling approach for microflow sensor. This paper is organised in the following manner. In Section 2, modelling of flow sensor is described. Section 3 describes experimental set-up; Section 4 concludes the paper.

2 Modeling of Flow Sensor

A basic principle of a design flowmeter is shown in Figure 1. This flowmeter type is called as Time – of – flight sensor. The time – of – flight sensor consists of a heater and one or more temperature sensors downstream. The heater is activated by current pulses. The transport of the generated heat is a combination of diffusion and forced convection. The resulting temperature field can be detected by temperature sensors located downstream. The sensor output is the time difference between the starting point of the generated heat pulse and the point in time at which a maximum temperature at the downstream sensor is reached.

The time – of – flight sensors have the same limitations as the intrusive type of calorimetric sensors: corrosion, erosion and leakage. Since the signal processing needs a short while to measure the time difference, this sensor type is not suitable for dynamic measurement.

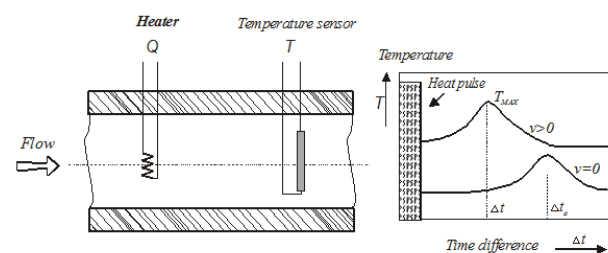


Fig.1 Time – of – flight sensor

The transport of the heat generated in line source through a fluid is governed by the energy equation:

$$\frac{\partial T}{\partial t} + v\nabla T = \left(\frac{\lambda}{\rho c}\right) \nabla^2 T + \frac{q'}{\rho c} \quad (1)$$

where T is the temperature, c is the specific heat at the constant pressure, ρ is the density, v is the kinematic viscosity of the fluid, λ is the thermal conductivity and q' (in $W\ m^{-3}$) is the amount of heat per unit of volume and time. The analytical solution of this differential equation for a pulse signal with input strength $q'o$ ($W\ m^{-1}$) is given in [4] as :

$$T(x, y, t) = \left(\frac{q'o}{4\pi\lambda t}\right) \exp\left\{-\frac{[(x-vt)^2]}{4at}\right\} \quad (2)$$

where a denotes the thermal diffusivity.

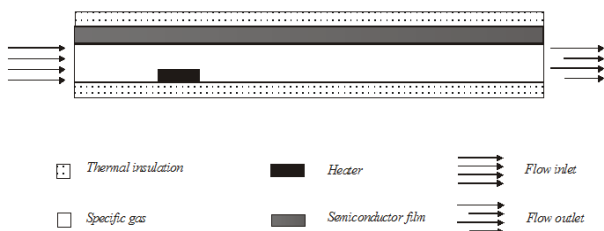


Fig.2 Modified version of Time – of – flight sensor

2.1 Basic configuration

The designed flowmeter was modified. The temperature in a classical design of the Time – of – Flight sensor is measured by temperature sensors located downstream. There are two or one sensors usually; these sensors measure a temperature in two points. In the modified version of designed flowmeter a temperature field is measured by semiconductor film. The temperature profile is dependent on gas velocity. The heater is activated periodically; the period of the heat pulses generation can be different for different velocity size of can be constant

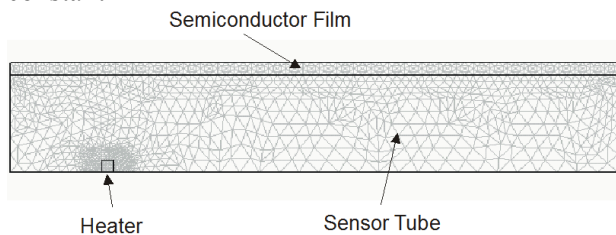


Fig.3 Partial view of the computational grid for the basic configuration

2.2 Modelling results

The properties of the modified time – of – flight sensor were simulated and verified for different flowing gases (CO_2 , air , $chlor$, N_2). The dependence of T_{MAX} on flow velocity v can be found in Fig. 5; the temperature T_{MAX} was measured in semiconductor film.

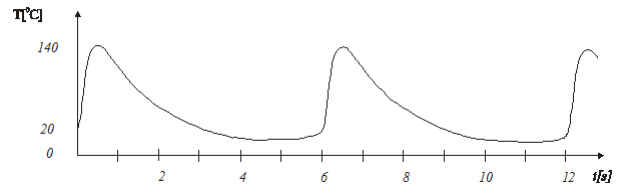


Fig.4 The time path of the temperature of the heater

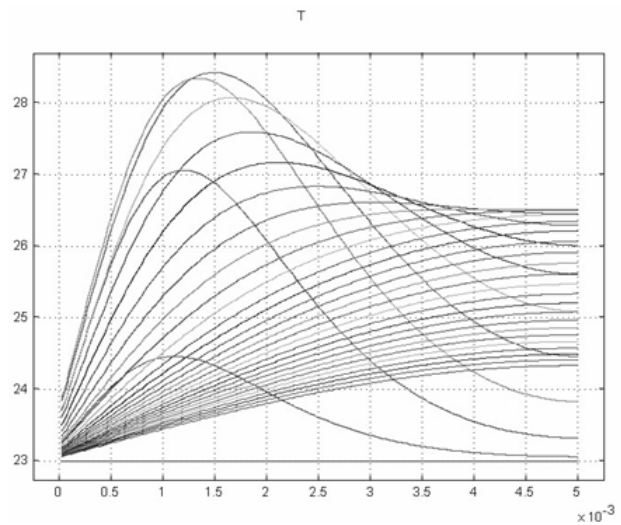


Fig.5 The profile in semiconductor film

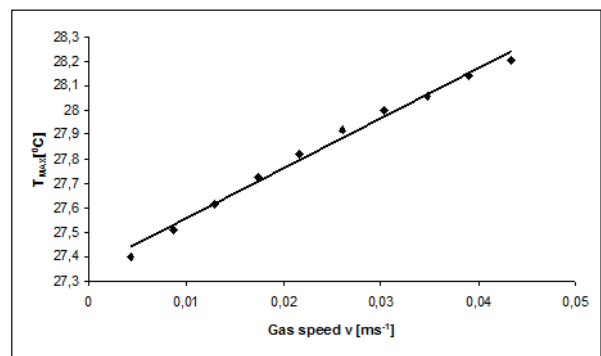


Fig.6 The time response of flow sensor: flow variation from 30ml/hr to 100ml/hr, the height of the fluid channel $d=0,8$ mm

3 Experimental Set - Up

The modified time-of-flight sensor consists of a heater placed on the pipe's floor and series of downstream sensors (semiconductor diodes) placed in the pipe's upper wall. The heater is activated for 1 second by a current pulse. The heat generated by the heater spreads with the flowing gas and leads into resistance changes on the diodes. The resistance

change upon each diode is measured as a voltage change by an A/D converter. From the particular points along the pipe is set the wave's heat profile which is scanned for the temperature maximum position. The flow volume is proportional to the position shift in time. The scheme drawing is shown in Fig. 7.

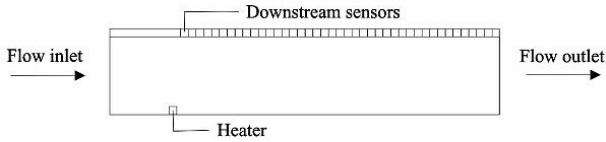


Fig.7 Experimental set-up of modified flow sensor

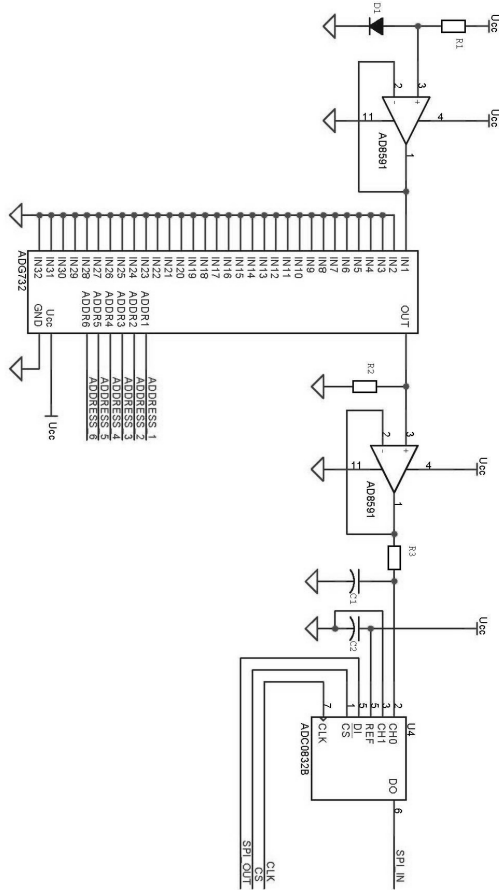


Fig.8 Block diagram of the modified sensor

The heater is made from iron wire leaf, the semiconductor array is made of silicon. The whole pipe is put into a polystyrene casing to become thermally insulated from the ambient temperature conditions. The length of the pipe body has been set as 5mm.

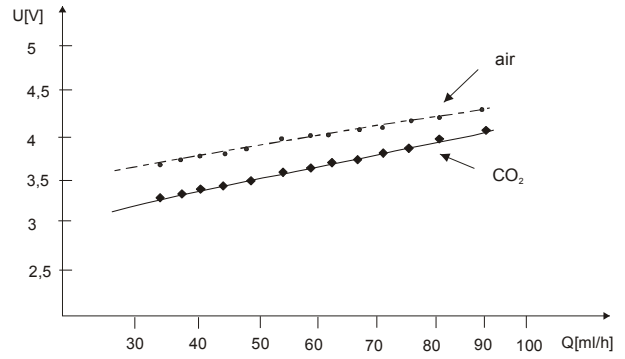


Fig.9 Static characteristic of modified sensor

4 Conclusion

This article describes properties of the modified time – of – flight sensor. The designed flowmeter has been used in a biochemical laboratory for study of reaction kinetic of a decomposition of sediments in waste water.

ACKNOWLEDGMENTS

The work has been supported by the Ministry of Education, Youth and Sports of the Czech Republic under the Research Plan No. MSM 7088352102 and by the European Regional Development Fund under the project CEBIA-Tech No. CZ.1.05/2.1.00/03. This support is very gratefully.

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