Application of He’s variational iteration method and Adomian decomposition method to solution for the fifth order Caudrey–Dodd–Gibbon (CDG) equation

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Abstract

In this work we use the He’s variational iteration method and Adomian decomposition method to solution N-soliton solutions for the fifth order Caudrey–Dodd–Gibbon (CDG) equation.

Keywords: Variation iteration method; Adomian decomposition method; Caudrey–Dodd–Gibbon (CDG) equation

1. Introduction

The theory of solitary waves has attracted much interest in recent years for treatment of PDEs describing nonlinear and evolution concepts. Nonlinear phenomena appear in many areas of scientific fields such as solid state physics, plasma physics, fluid dynamics, mathematical biology and chemical kinetics. The nonlinear problems are characterized by dispersive effects, dissipative effects, convection–advection, and diffusion process. A broad class of analytical solutions methods, such as inverse scattering method, Ba‘cklund transformation method, Hirota’s bilinear scheme [1–6], Hereman’s method [7,8], pseudo spectral method, Jacobi elliptic method, Painleve´ analysis [9], and other methods, were used to handle these problems. However, some of these analytical solutions methods are not easy to use because of the tedious work that it requires. This paper is concerned with the multiple-soliton solutions of the fifth order nonlinear Caudrey–Dodd–Gibbon (CDG) equation [10,11]

$$u_t + u_{xxxx} + 30uu_{xx} + 30u_xu_{xx} + 180u^2u_x = 0$$  

(1)

with $u(x, t)$ is a sufficiently often differentiable function. It is well-known that this equation is completely integrable. This means that it has multiple-soliton solutions. The CDG equation possesses the Painleve´ property as proved by Weiss in [9]. A useful study is introduced in [9] using the Painleve´ property and the Ba‘cklund transformation in handling the CDG equation and other equations as well. It was found in [9] that the CDG equation (1) has the Backlund transformation

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\[ u = \frac{\partial^2}{\partial x^2} \ln \Phi + u_2 \]  
(2)

where \( u_2 \) satisfies the CDG equation, and

\[ u_2 = -\frac{1}{6} \frac{\Phi_{xxx}}{\Phi_x} \]  
(3)

and

\[ \frac{\Phi_t}{\Phi_x} + \frac{\partial^2}{\partial x^2} (\Phi_x; x) + 4(\Phi_x; x)^2 = 0 \]  
(4)

The last two equations can be expressed as the Lax pair

\[ \Phi_{xxx} + 6u_2 \Phi_{xx} = 0; \]  
(5)

\[ \Phi_t + 18u_2 \Phi_{xx} + 6(u_2^2 - u_2 xx)\Phi_x = 0; \]  
(6)

The objective of this work is to further complement other studies related to the CDG equation. The tanh method [12–17], and the tanh–coth method [18,19] will be used to stress its power in the determination of single-soliton solution and other travelling wave solutions. We aim to use Adomian decomposition method and variation iteration method to solve this equation.

2- Basic idea of He’s variational iteration method

To clarify the basic ideas of VIM, we consider the following differential equation:

\[ Lu + Nu = g(t), \]  
(7)

where \( L \) is a linear operator, \( N \) a nonlinear operator and \( g(t) \) an inhomogeneous term.

According to VIM, we can write down a correction functional as follows:

\[ u_{n+1}(t) = u_n(t) + \int_0^t \lambda (Lu_n(\tau) + Nu_n(\tau) - g(\tau)) d\tau, \]  
(8)

Where \( \lambda \) is a general Lagrangian multiplier which can be identified optimally via the variational theory. The subscript \( n \) indicates the \( n \)th approximation and \( \tilde{u}_n \) is considered as a restricted variation \( \delta \tilde{u}_n = 0 \).

a. VIM implement for this equation:

we first consider the application of VIM Caudrey–Dodd–Gibbon(CDG) equation:

\[ u_t + u_{xxxxx} + 30uu_{xxx} + 30u_x u_{xx} + 180u^2 u_x = 0; \]  
(9)
with the initial conditions of:
\[ u_0(x,t) = \mu^2 \sec h^2(\mu x); \quad (10) \]

To earn general Lagrangian multiplier (\( \lambda \)) we put coefficient of \( u_t \) or \( u_x \) equal zero. Where prime indicates a differential with respect to \( x \) and dot denotes a differential with respect to \( t \). We earn \( \lambda \) respect to \( t \). After some calculations, we obtain the following stationary conditions in equ(10a) and (10b):

\[ 1 + \lambda (\tau)|_{\tau=0} = 0, \quad (10a) \]
\[ \lambda (\tau) = -1, \quad (10b) \]

Its correction variational functional in \( x \) and \( t \) can be expressed, respectively, as follows:

\[ u_{n+1}(x,t) = u_n(x,t) + \int_0^\tau \lambda \left( \frac{\partial}{\partial \tau} u_n(x,t) + \frac{\partial^5}{\partial x^5} u_n(x,t) + 30 \frac{\partial}{\partial x} u_n(x,t) + \frac{\partial^2}{\partial x^2} u_n(x,t) \right) d\tau \quad (9) \]

We start with the initial approximation of \( u(x,0) \) given by Eq. (4). Using the above iteration formulas (9), we can directly obtain the other components as follows:

\[ u_1(x,t) = \frac{\mu^2 (\cosh(\mu x) + 32 t \mu^5 \sinh(\mu x))}{\cosh^3(\mu x)}, \quad (11) \]
\[ u_2(x,t) = \frac{1}{\cosh(\mu x)^{10}} \mu^2 (\cosh(\mu x)^8 + 32 \mu^5 \sinh(\mu x) t \cosh(\mu x)^7 \]
\[ + 163840 \mu^{15} \sinh(\mu x) t^3 \cosh(\mu x)^3 - 614400 \mu^{15} \sinh(\mu x) t^3 \cosh(\mu x)^3 \]
\[ - 7372800 \mu^{20} t^4 \cosh(\mu x)^2 + 2949120 \mu^{20} t^4 \cosh(\mu x)^4 + 4423680 \mu^{20} t^4 \]
\[ + 491520 \mu^{15} \sinh(\mu x) t^3 \cosh(\mu x)^3 + 512 \mu^{10} t^2 \cosh(\mu x)^8 - 768 \mu^{10} t^2 \cosh(\mu x)^6 \quad (13) \]

And continue then we show the last result in fig(1a)

3- Basic idea of Adomian decomposition method

We begin with the equation

\[ Lu + R(u) + F(u) = g(t) \quad (14) \]

where \( L \) is the operator of the highest-ordered derivatives with respect to \( t \) and \( R \) is the remainder of the linear operator. The nonlinear term is represented by \( F(u) \). Thus we get

\[ Lu = g(t) - R(u) - F(u) \quad (15) \]
The inverse \( L^{-1} \) is assumed an integral operator given by

\[
L^{-1} = \int_{0}^{t} (\bullet) dt
\]  

(16)

The operating with the operator \( L^{-1} \) on both sides of Eq. (15) we have

\[
u = f_0 + L^{-1}(g(t) - R(u) - F(u))
\]  

(17)

where \( f_0 \) is the solution of homogeneous equation

\[
Lu = 0
\]  

(18)

involving the constants of integration. The integration constants involved in the solution of homogeneous equation (18) are to be determined by the initial or boundary condition according as the problem is initial-value problem or boundary-value problem.

The ADM assumes that the unknown function \( u(x,t) \) can be expressed by an infinite series of the form

\[
u(x,t) = \sum_{n=0}^{\infty} u_n(x,t)
\]  

(19)

and the nonlinear operator \( F(u) \) can be decomposed by an infinite series of polynomials given by

\[
F(u) = \sum_{n=0}^{\infty} A_n
\]  

(20)

where \( u_n(x,t) \) will be determined recurrently, and \( A_n \) are the so-called polynomials of \( u_0, u_1, ..., u_n \) defined by

\[
A_n = \frac{1}{n!} \frac{d^n}{d \lambda^n} \left[ F \left( \sum_{i=0}^{\infty} \lambda^i u_i \right) \right]_{\lambda=0}, \quad n = 0,1,2...
\]  

(21)

It is now well known in the literature that these polynomials can be constructed for all classes of nonlinearity according to algorithms set by Adomian [10,15] and recently developed by an alternative approach in [8,9,16,17].

**b. ADM implement for this equation:**

we solve this equation

\[
u_{n+1}(x, t) = \int_{0}^{t} \begin{pmatrix}
-\frac{\partial^5}{\partial x^5} u_n(x, \tau) - 30 \frac{\partial}{\partial x} u_n(x, \tau) \frac{\partial^2}{\partial x^2} u_n(x, \tau) - 30u_n(x, \tau) \frac{\partial^3}{\partial x^3} u_n(x, \tau) \\
-180u_n(x, \tau)^2 \frac{\partial}{\partial x} u_n(x, \tau)
\end{pmatrix} d\tau
\]  

(22)
We solve with this way CDG equation and continue

\[ u_1(x,t) = \frac{32\mu' t \sinh(\mu x)}{\cosh^3(\mu x)} \]  \hspace{1cm} (23)

\[ u_2(x,t) = \frac{1}{\cosh(\mu x)^{10}} (128\mu^2 t^2 (23040\mu^{10} t^2 \cosh(\mu x)^4 - 57600\mu^{10} t^2 \cosh(\mu x)^2 \\
+ 34560\mu^2 t^2 + 1280\mu^5 \sinh(\mu x) t \cosh(\mu x)^5 - 7680\mu^5 \sinh(\mu x) t \cosh(\mu x)^3 \\
+ 7680\mu^6 \sinh(\mu x) t \cosh(\mu x)^4 + 4\cosh(\mu x)^8 - 126\cosh(\mu x)^2 + 420\cosh(\mu x)^4 \\
- 315\cosh(\mu x)^2) ) \]  \hspace{1cm} (24)

\[ u(x,t) = \mu^2 \sec^2(\mu x) + \frac{32\mu' t \sinh(\mu x)}{\cosh^3(\mu x)} + \frac{1}{\cosh(\mu x)^{10}} (128\mu^{12} t^2 \\
(23040\mu^{10} t^2 \cosh(\mu x)^4 - 57600\mu^{10} t^2 \cosh(\mu x)^2 + 34560\mu^{10} t^2 \\
+ 1280\mu^5 \sinh(\mu x) t \cosh(\mu x)^5 - 7680\mu^5 \sinh(\mu x) t \cosh(\mu x)^3 \\
+ 7680\mu^6 \sinh(\mu x) t \cosh(\mu x)^4 + 4\cosh(\mu x)^8 - 126\cosh(\mu x)^2 + 420\cosh(\mu x)^4 \\
- 315\cosh(\mu x)^2) ) \]  \hspace{1cm} (25)

We sum \( u_i \) in equ 25 and earn the results according to \( \mu = 1, 1.5, 2, 3 \) in figures(1,2,3,4)

1a

1b

Fig. 1. For the solitary wave solution with the first initial conditions (4) of Eq. (1), VIM result for \( u(x,t) \) is, respectively (1b) and ADM(1b), with \( \mu = 1 \)
Fig. 2. For VIM result for $u(x,t)$ is, respectively (1b) and ADM(1b), with $\mu = 1.5$

Fig. 3. VIM result for $u(x,t)$ is, respectively (1b) and ADM(1b), with $\mu = 2$

Fig. 4. VIM result for $u(x,t)$ is, respectively (1b) and ADM(1b), with $\mu = 3$
We compare 2-D figures of VIM and ADM for different values of $\mu$:

(5) $\mu = 1$

(6) $\mu = 1.5$

(7) $\mu = 2$

(8) $\mu = 3$

4- Conclusions

In this paper, He’s variational iteration method has been successfully applied to find the solution CDG equations. Both of methods show that the results are in excellent agreement with together and the obtained solutions are shown graphically. In our work, we use the Maple Package to calculate the functions obtained from the variational iteration method and adomian decomposition method. An interesting point about ADM is that with the fewest number of iterations or even in some cases, once, it can converge to correct results.

References